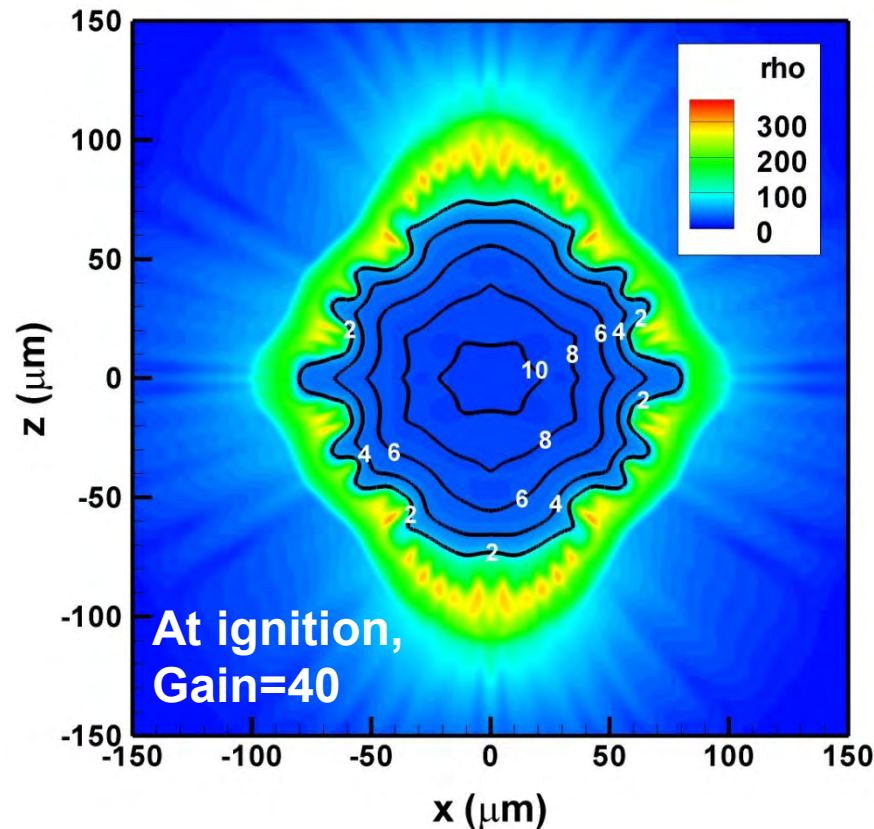


Polar-Drive Hot-Spot Ignition Design for the National Ignition Facility



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Simulations indicate that polar drive (PD) is a promising ignition alternative for the NIF

- **A 2-D simulation of the polar-drive hot-spot point ignition design shows a gain of 40 with target and laser nonuniformities**
- **This design employs three relaxation pickets for adiabat shaping and to facilitate experimental shock timing**
- **This design employs a thick plastic ablator to mitigate the effects of hot-electron preheat**

Contributors



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P. W. McKenty, P. B. Radha and A. Shvydky**

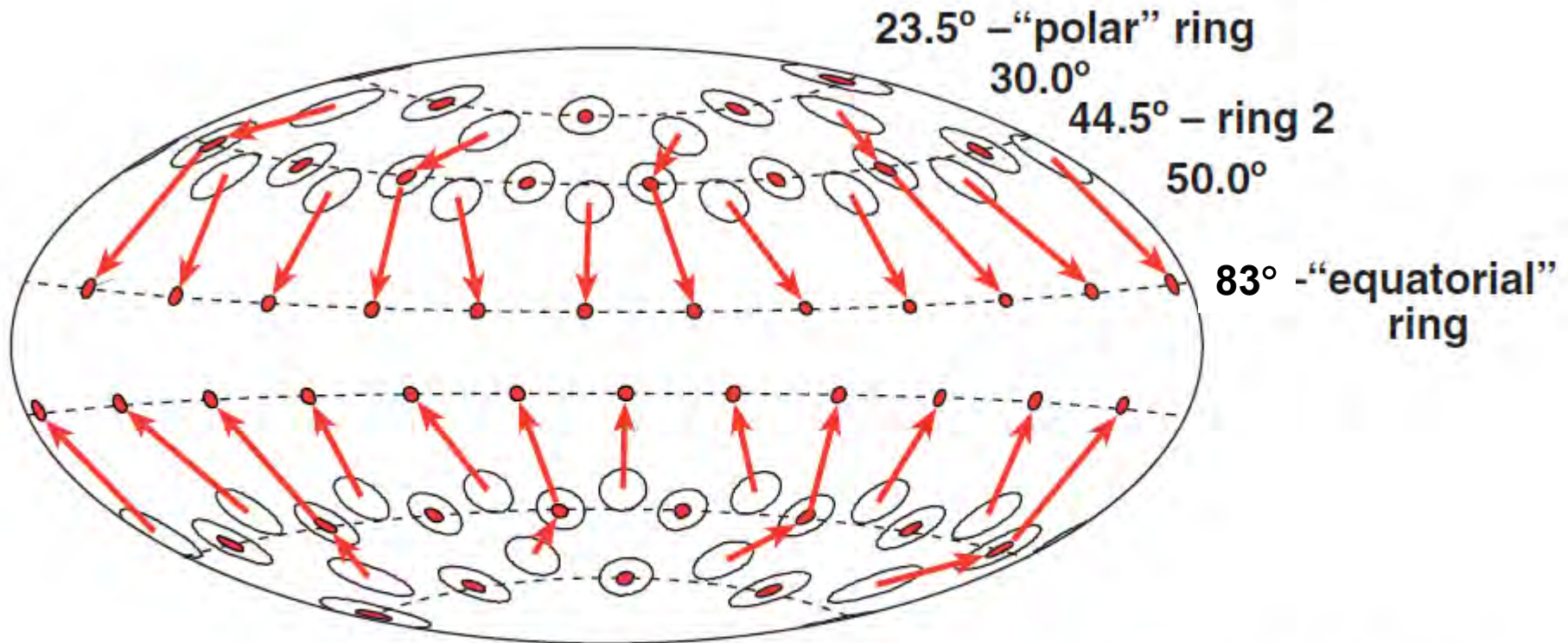
**University of Rochester
Laboratory for Laser Energetics**

Outline



- **Polar Drive: Background and Lessons Learned**
- **The elements of the new Hot Spot, Triple-Picket Polar-Drive point design**

In polar drive, the NIF x-ray-drive beams are pointed to three latitude rings in each hemisphere on the target



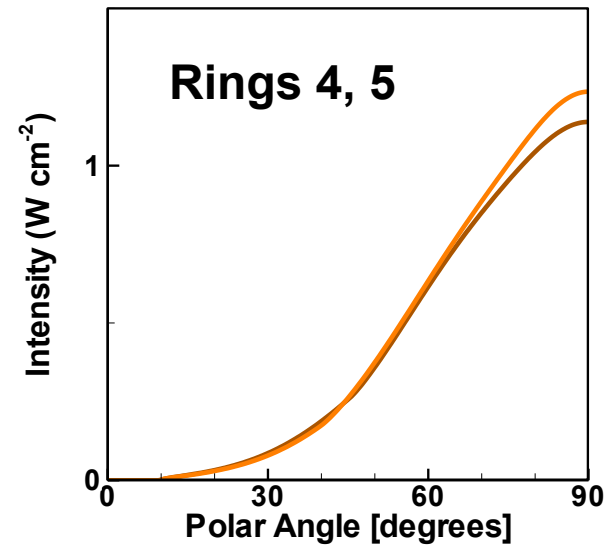
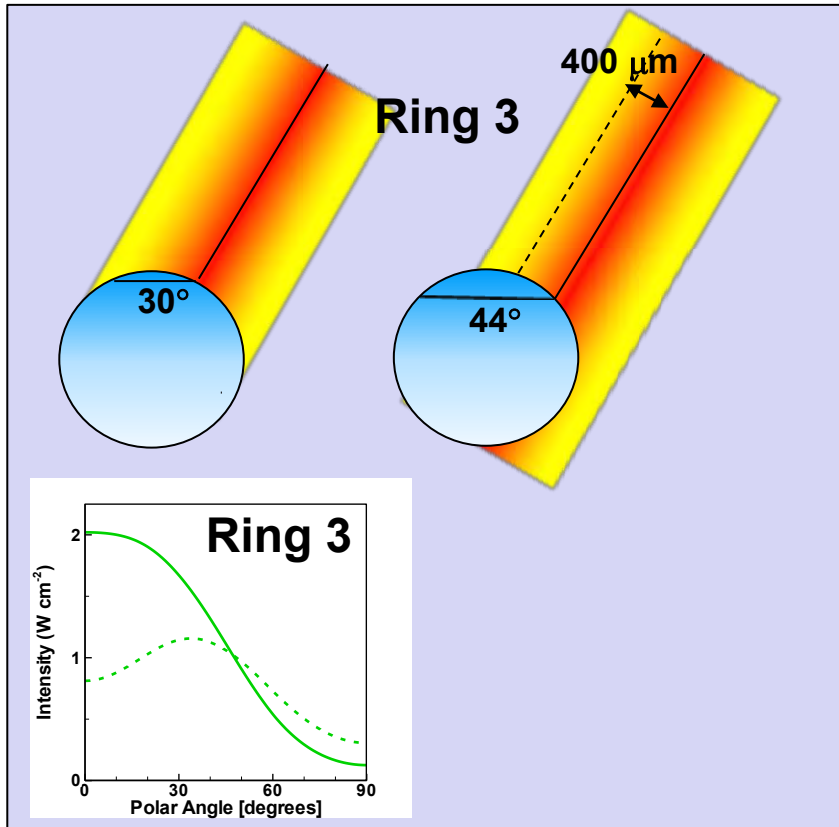
Polar Drive

○ X-ray-drive port

● PD pointing

- This is also relevant to IFE, insofar as polar port geometry is desired

Repointing corresponds to a lateral translation of the beam in the target plane



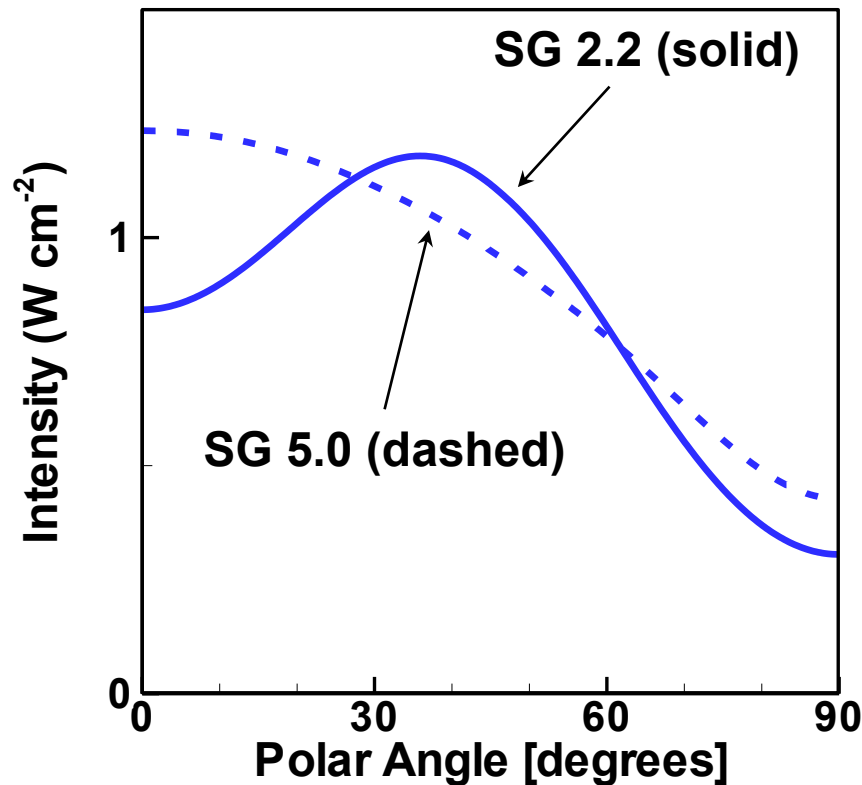
**Repointing rings 4,5
moves energy to the equator**

Oblique irradiation near the equator is at lower densities, causing

- reduced absorption
- reduced hydrodynamic efficiency and
- lateral heat flow

Lower super-Gaussian beam-shape orders offer greater control of the energy density on the target

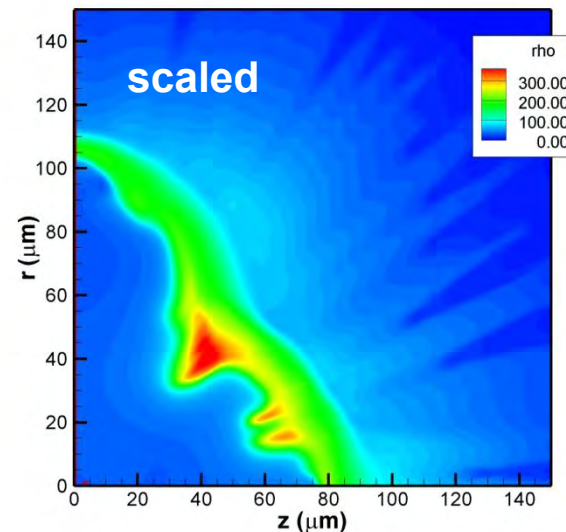
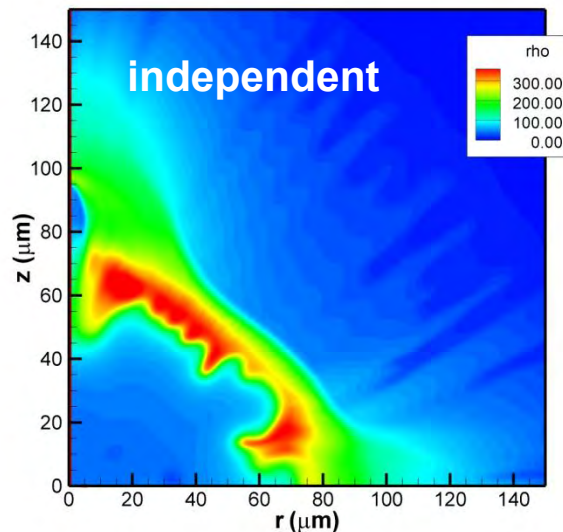
Ring 2, Repointed from 30° to 44°



- Less energy is spilled over the horizon when lower super-Gaussian-order beams are repointed

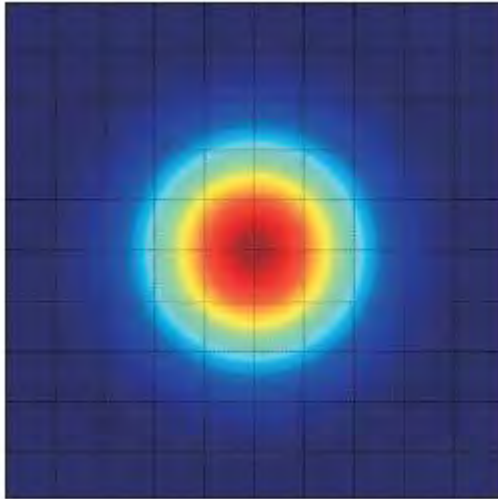
Independent ring pulse shapes are used to compensate for variations in angle of incidence

- The equatorial rings are driven at a higher power than the other rings
- The mid-latitude rings must be lowered due to beam overlap
- The polar ring power is raised for the same reason
- Pickets and drive pulse required different relative ring powers; using ring pulse shapes which are multiples of each other reduces this target's gain by 40%

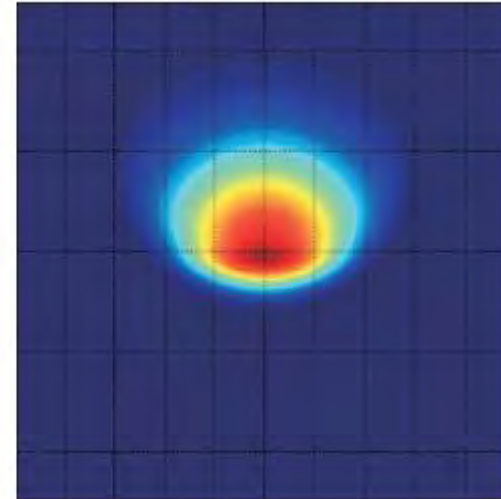


Equatorial beam coupling can be increased using tailored phase plates

Pole and mid-latitude

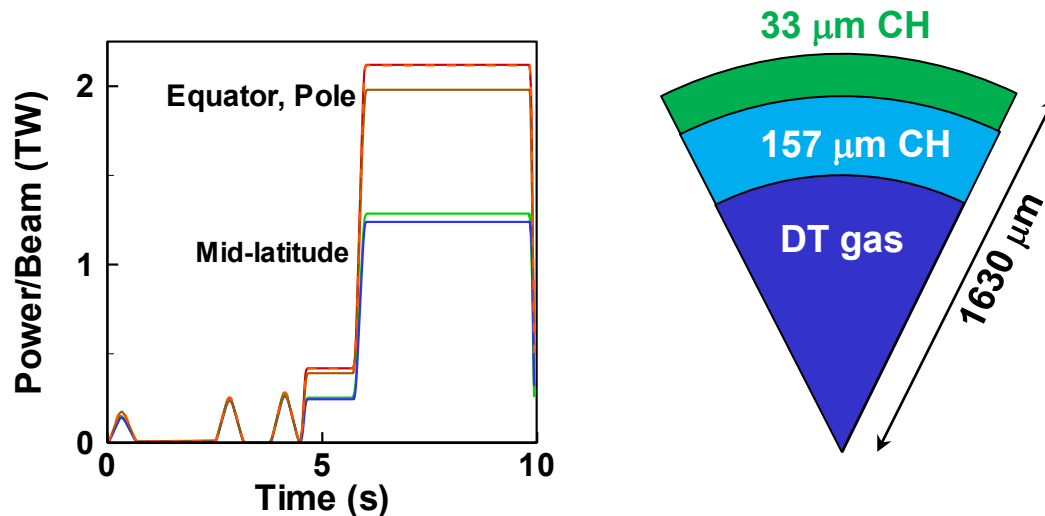


Equatorial



- The equatorial spot shape combines a round spot with an elliptical spot to mitigate loss of coupling near the equator
- The resulting spot is asymmetric to reduce loss of energy over the horizon

The triple-picket design uses a multiple-picket, multiple-shock laser pulse



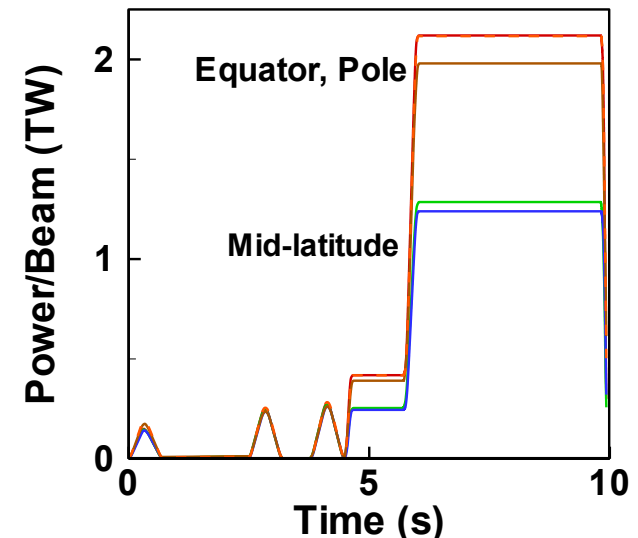
- This design is based on the triple-picket design* used on OMEGA to achieve an areal density of nearly 300 mg/cm²**
- A thick CH ablator is used to minimize the risk of hot-electron preheat
- Individual pulse energies lie within NIF limits for energy (9.3 kJ/beam) and power/beam

* V. N. Goncharov *et al.*, Phys. Rev. Lett. **104**, 165001 (2010).

** T. C. Sangster *et al.*, Phys. Plasmas **17**, 056312 (2010).

A relaxation-picket pulse is used with a rapid-rise drive pulse

- OMEGA experiments have demonstrated that picket pulses are better suited to experimental shock tuning because of greater pulse reproducibility*
- Use of a rapid-rise drive pulse reduces uncertainties in shock timing caused by low-adiabat slow-rise pulses
- Relaxation pickets, for which the laser power is small or zero between the pickets, allow greater adiabat shaping and greater shell stability**
- Subsequent pickets must have diminishing relaxation times, limiting the number of pickets
- A “step” pulse is used at the start of the drive to allow a lower drive-pulse power



* T. R. Boehly *et al.*, *Phys. Plasmas* **16**, 056302 (2009).

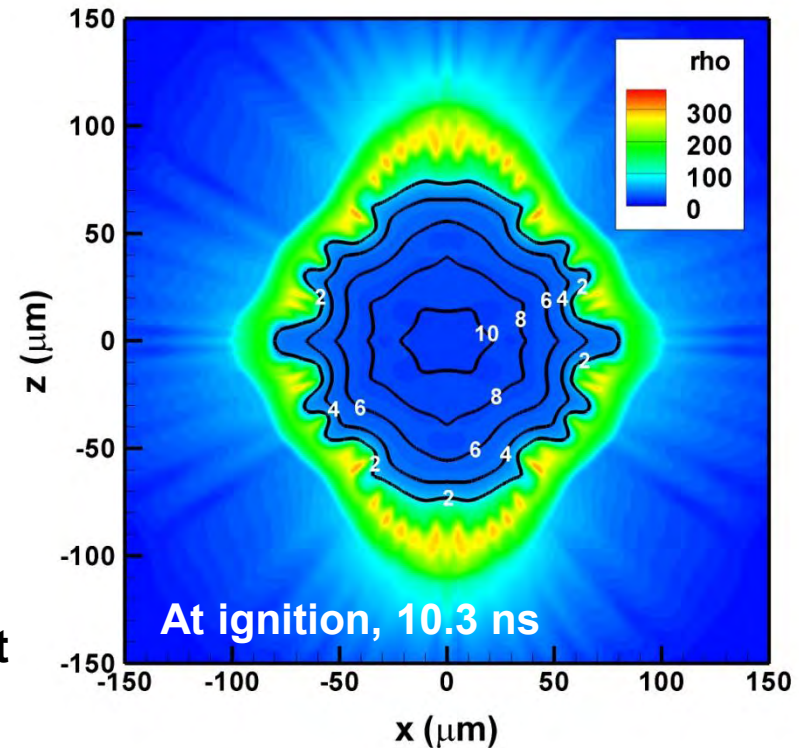
** K. Anderson and R. Betti, *Phys. Plasmas* **11**, 5 (2004).

The triple-picket PD design with target and beam nonuniformities and Multi-FM beam smoothing* achieves a gain of 40

- One- μm RMS ice roughness is included as well as single-beam imprint ($\ell \in [2, 100]$), 8% RMS power imbalance, 30-ps RMS beam mistiming, 50- μm beam mis-pointing and surface roughness

Energy	1.54 MJ
Gain	40
v_{imp}	440 $\mu\text{m}/\text{ns}$
Shell integrity	26%
α	2
Peak ρR	1.42 g/cm^2

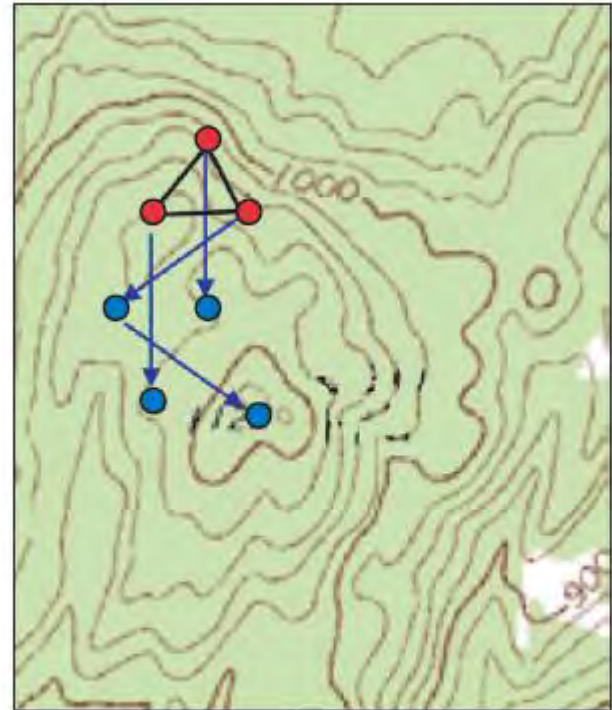
- Flux-limited diffusive thermal transport was used (6%)
- Gas density = 0.225 g cm^{-3}



* See Marozas, next talk

The triple-picket PD ignition design was optimized in 1-D with a downhill simplex method

- This points in the pulse shape (power, time) and target dimensions were optimized
- This design was optimized to maximize gain while requiring peak power not to exceed damage threshold limits, in turn fixing the implosion velocity
- This method allows for tuning of more variables than would be feasible by hand (in this case, 12)
- Other metrics have proven useful: $f(\text{Gain}, \text{IFAR}, \rho R)$, etc.

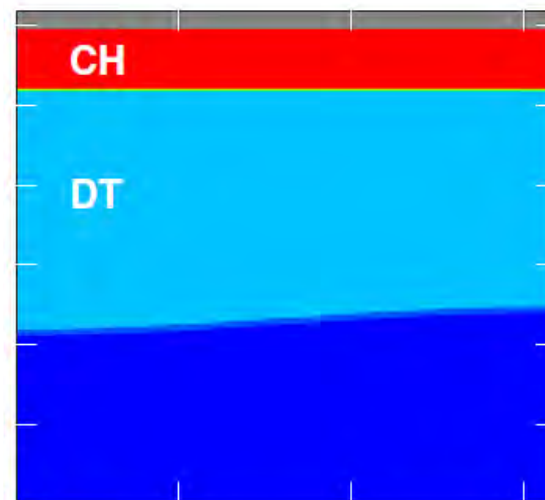
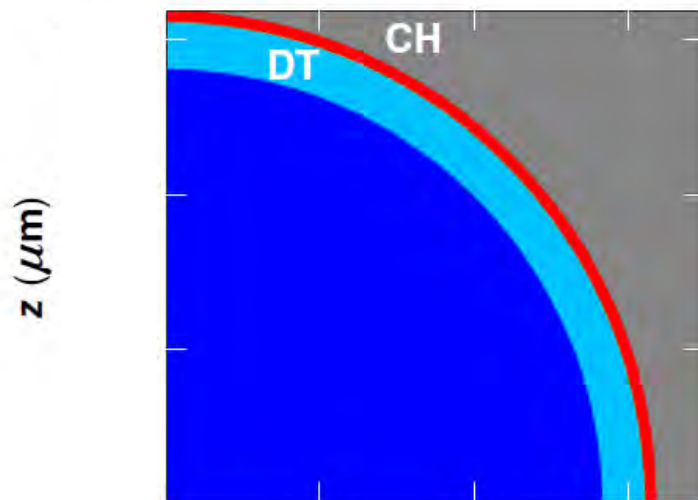


A simplex on a topographical map optimizing for maximum height

An $\ell=2$ ice-layer “shim” is used to lower the equatorial mass



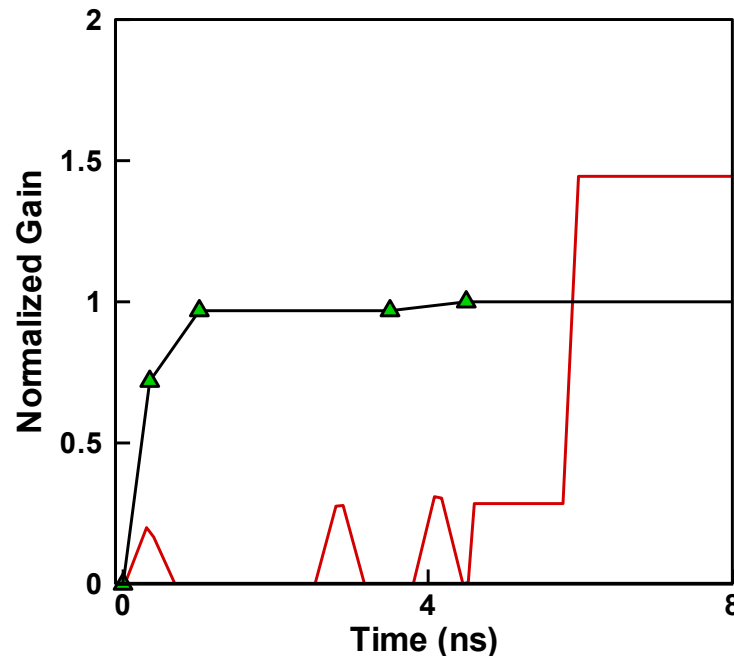
- An 11.5- μm $\ell=2$ ice-layer “shim” is used to lower the equatorial mass and compensate for reduced equatorial drive
- This perturbation could be introduced by shimming the cryogenic layering sphere itself or adding an IR source around the equator
- The resulting perturbation would be repeatable *but not necessarily precise*
- A 10- μm shim allows a $\sim 10\%$ reduction in equatorial beam power, allowing greater overall power while remaining below laser damage thresholds



Simulations show little gain degradation when SSD is only active for the first picket



- **Motivation:** “Turning off” SSD early reduces the risk of damage to the laser
- Single-beam smoothing asymptotes on timescales comparable to 1 ns (Marozas, this session)



Future work includes modeling of plasma effects



- A 2-D Schurtz-type nonlocal thermal transport model has been implemented in *DRACO* by G. Moses and his team at U. Wisconsin and is currently being tested
- A cross-beam energy transfer package is under development for *DRACO 2D*
- This design will be simulated in *HYDRA* in 2D and 3D
 - Enhancements to *HYDRA*'s 3D ray trace are underway for use in direct-drive simulations
- A scaled version of the design is under development

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Sensitivity (1-D)

- ...