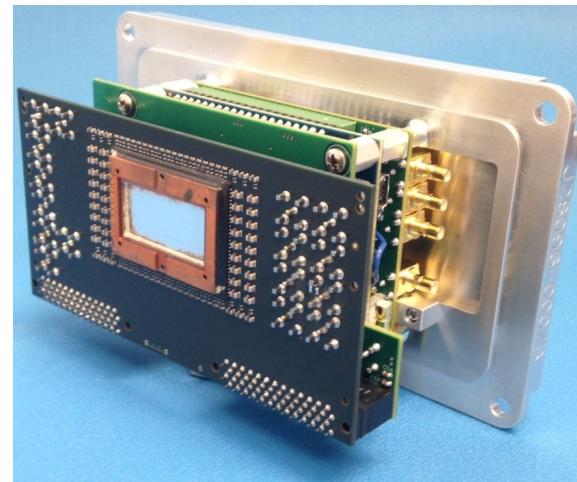


October 6, 2015

## First Use of Hybrid CMOS Cameras on Z and NIF



John Porter on behalf of the UXI project team  
Sandia National Laboratories, [jlporte@sandia.gov](mailto:jlporte@sandia.gov)

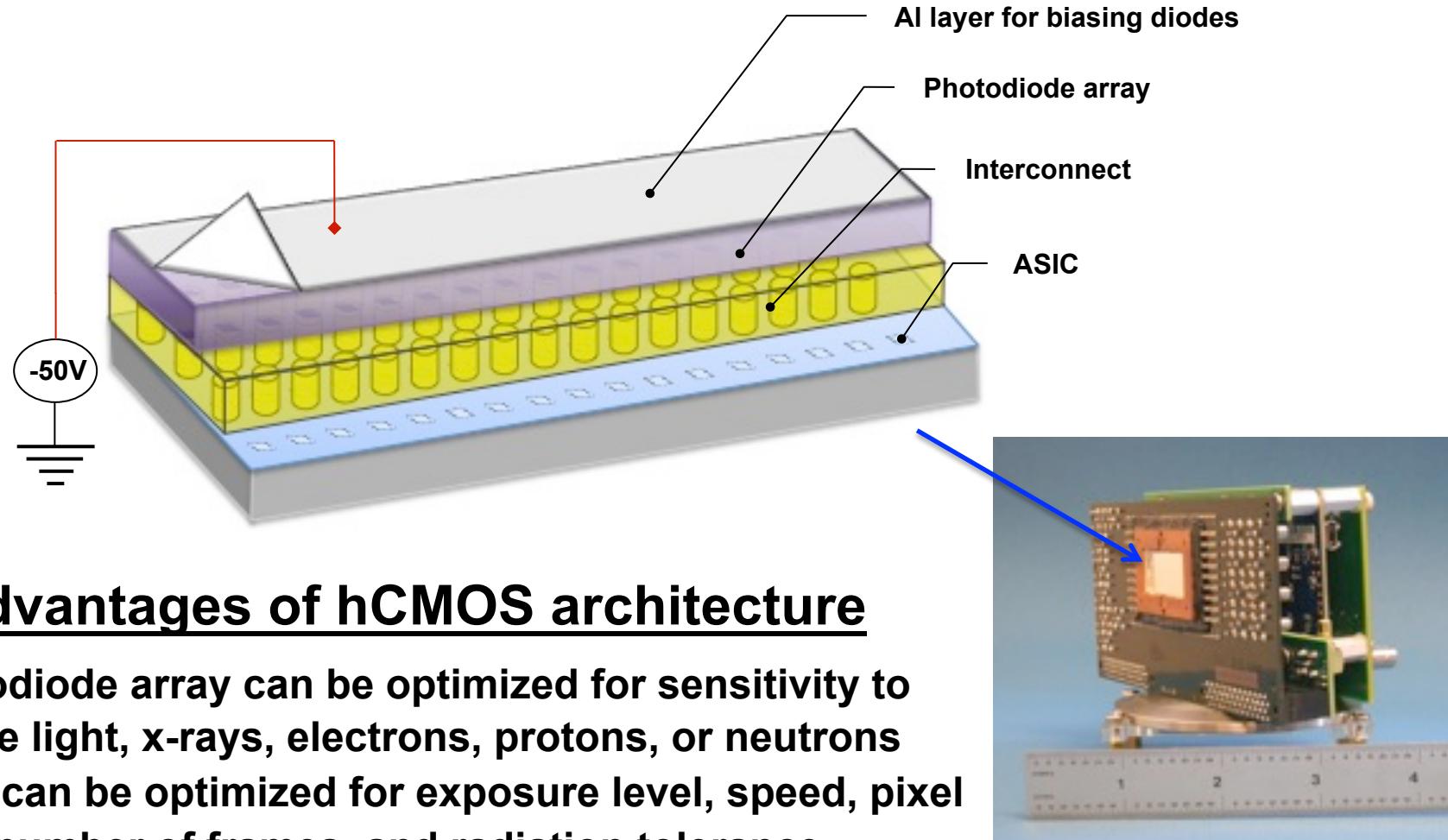
# Collaborators

- **Sandia**
  - **Photodiodes:** Doug Trotter, Rex Kay, and Quinn Looker
  - **ASIC:** Liam Claus, Gideon Robertson, Marcos Sanchez
  - **Packaging:** Lu Fang
  - **Semiconductor fabrication:** MESA Fab team and Zipptronix
  - **Characterization & Z integration:** John Stahoviak, Mark Kimmel, Joel Long, and Larry Ruggles
- **LLNL**
  - **NIF integration:** Hui Chen, Nathan Palmer, Jarom Nelson, Sukhdeep Heerey, and Perry Bell
- **GA**
  - **NIF integration:** Terry Hilsabeck and Joe Kilkenny

## Outline

- **Hybrid CMOS camera overview**
- **Characterization of “Furi” camera performance**
- **Images from Z & NIF**
- **Future plans and conclusion**

# A hybrid CMOS detector enables independent optimization of the radiation sensor and Integrated Circuit



## Advantages of hCMOS architecture

- Photodiode array can be optimized for sensitivity to visible light, x-rays, electrons, protons, or neutrons
- ASIC can be optimized for exposure level, speed, pixel size, number of frames, and radiation tolerance
- Optimized cameras can be created by interconnecting different combinations of ASICs and photodiode arrays

# Evolution of Sandia's hCMOS camera designs

	<b>Griffin</b>	<b>Furi</b>	<b>Hippogriff</b>	<b>Icarus</b>	<b>Acca</b>
<b>Year</b>	2012	<b>2013</b>	2014	2015	2016
<b>Pixel pitch</b>	25µm	<b>25µm</b>	25µm	25µm	25µm
<b>Min. gate time</b>	1.5ns	<b>1.5ns</b>	2ns	1.5ns (TBD)	1ns
<b>Pixels</b>	15 x 128	<b>448 x 1024</b>	448 x 1024	512 x 1024	512 x 512
<b>Frames/pixel</b>	4	<b>2</b>	2 , 4, or 8 (interlaced)	4	8
<b>Sensor types</b>	500-900 nm, 0.7-6 keV	<b>500-900 nm, 0.7-6 keV</b>	500-900 nm, 0.7-9 keV	400-900 nm, 0.3-9 keV 4keV electrons	350-900 nm, 0.2-9 keV 2keV electrons
<b>Dynamic range</b>	1000x, 1500-1.5x10 <sup>6</sup> e <sup>-</sup>	<b>1000x, 1500-1.5x10<sup>6</sup> e<sup>-</sup></b>	1000x, 1500-1.5x10 <sup>6</sup> e <sup>-</sup>	1000x, 500-5x10 <sup>5</sup> e <sup>-</sup>	1000x, 500-5x10 <sup>5</sup> e <sup>-</sup>
<b>Tiling option</b>	No	<b>No</b>	No	No	Yes
<b>CMOS process</b>	350nm	<b>350nm</b>	350nm	350nm	130nm
<b>Status</b>	completed	<b>completed</b>	completed	in packaging	in design

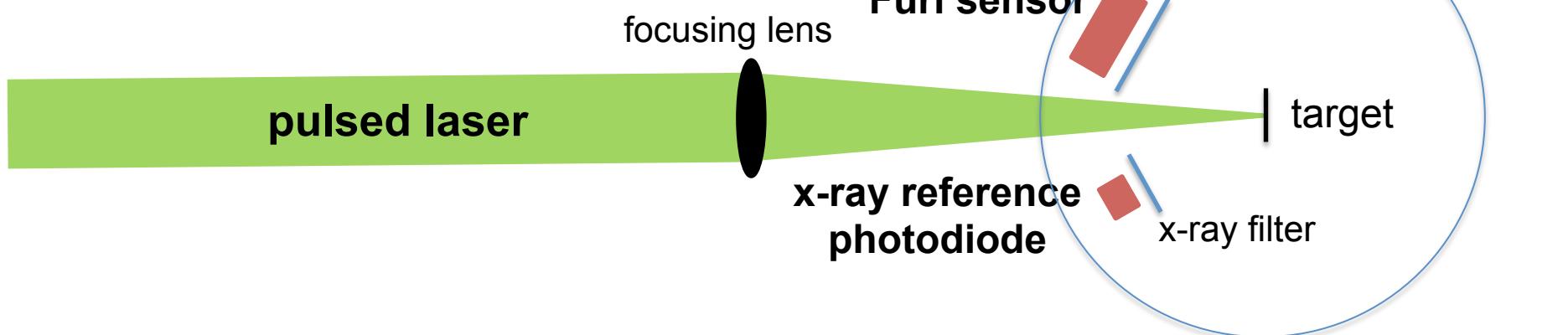
# We use a pulsed laser to characterize camera response to either x-rays or visible illumination

Laser wavelength: 532 nm (frequency doubled)

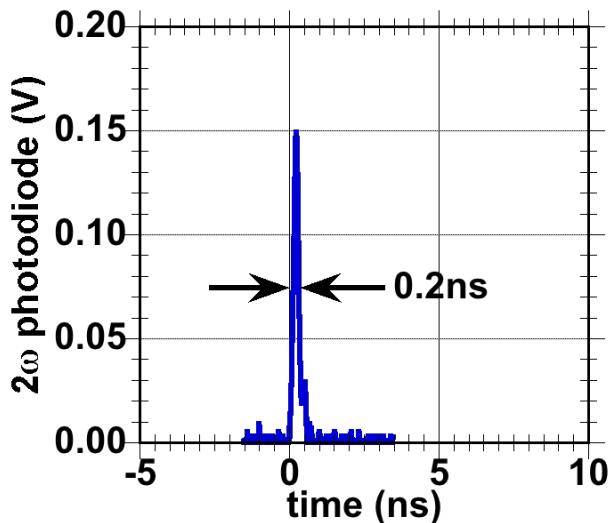
Laser  $2\omega$  energy: 0.1  $\mu$ J - 15 J (user selectable)

Pulse duration & shape: 0.2 - 7 ns (user selectable)

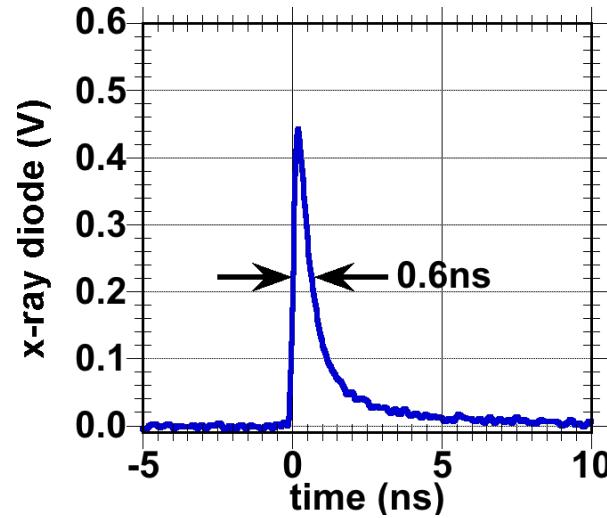
X-ray targets: Ti @ 4.7 keV, Mg @ 1.5 keV



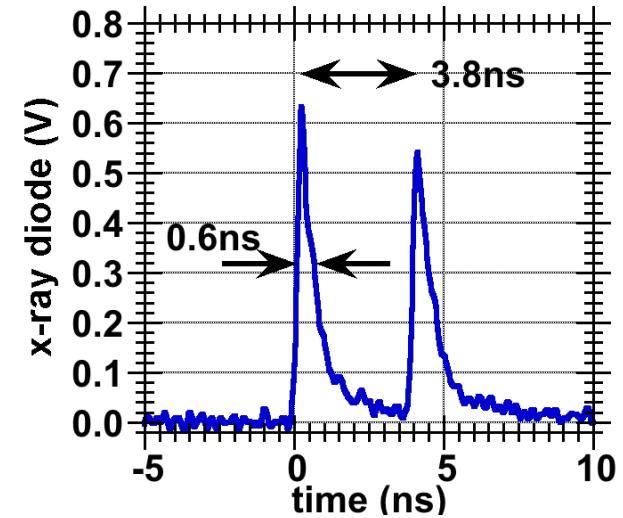
**200ps visible illumination**



**600ps x-ray illumination**

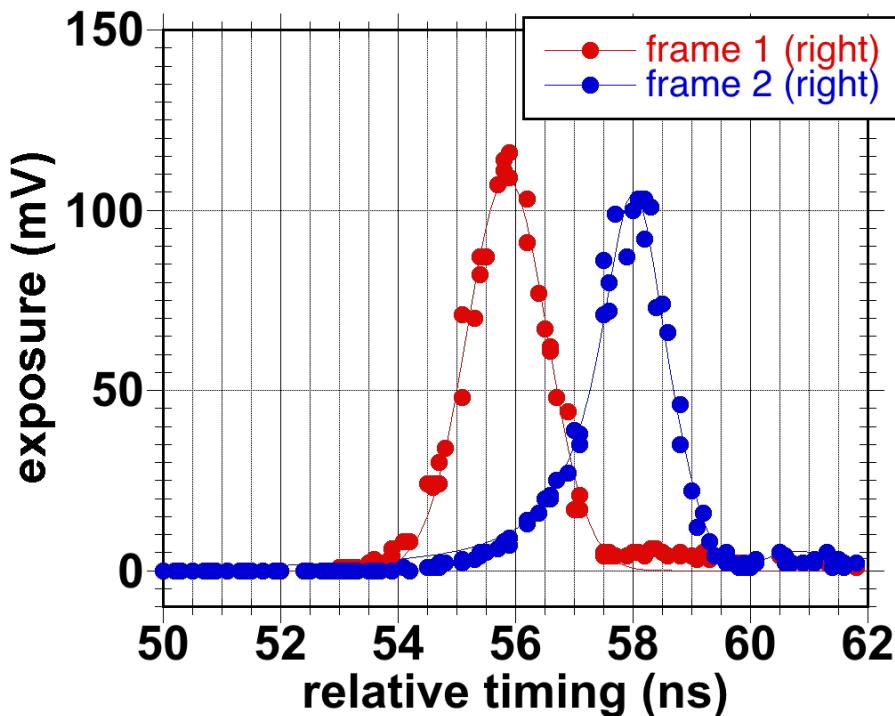


**2-pulse x-ray illumination**

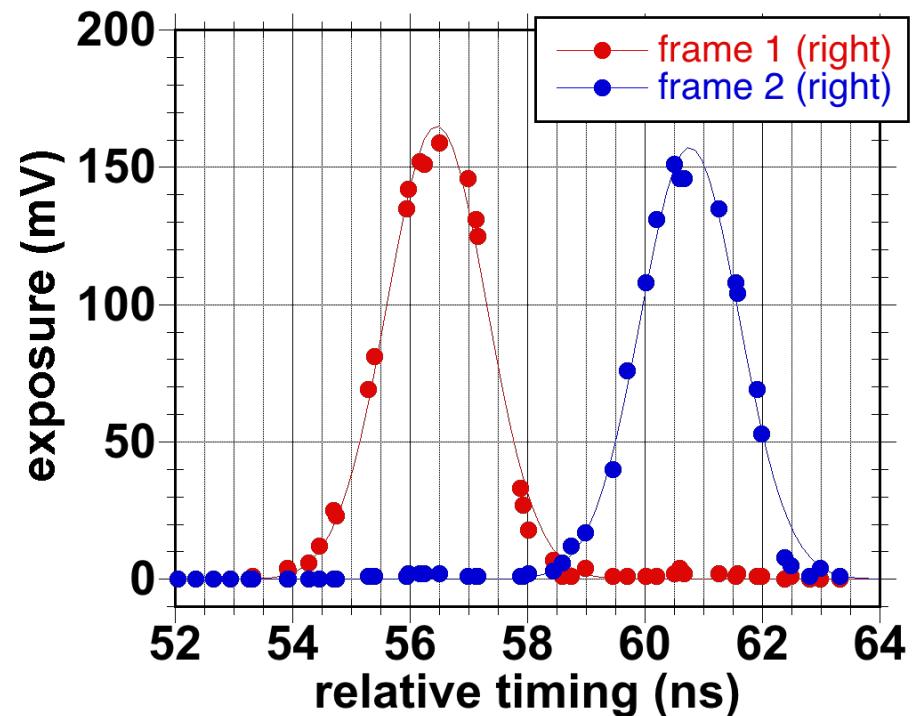


# Example of Furi time-response measurements using 200ps pulsed visible illumination

1/1ns timing mode, FG5 sensor



2/2ns timing mode, FG5 sensor

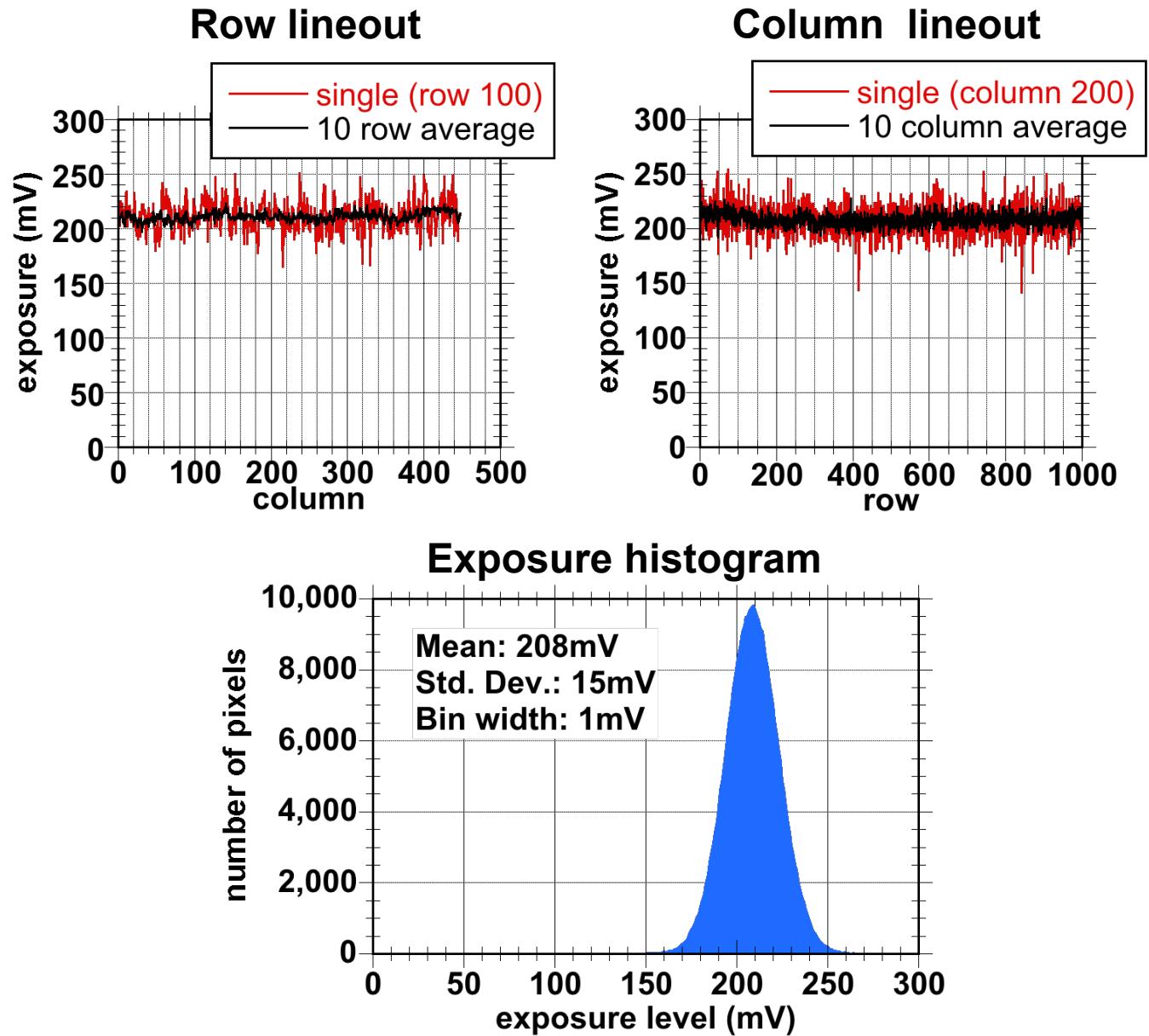
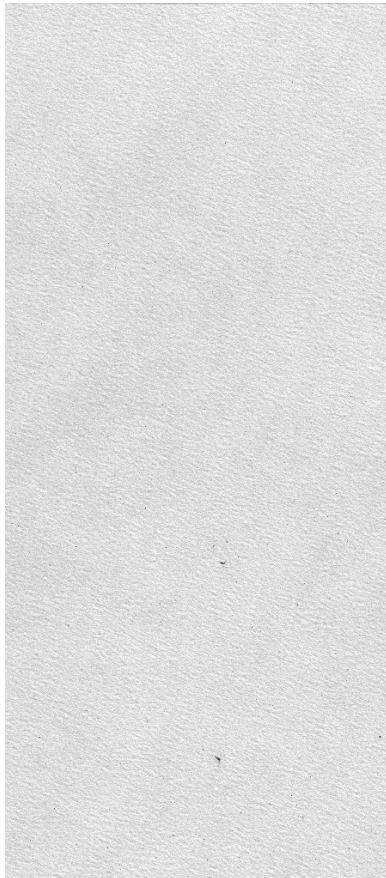


	FWHM (ns)	Frame $\Delta t$ (ns)	left/right $\Delta t$ (ns)
frame 1	1.6		0.9
frame 2	1.6	2.1	0.8

	FWHM (ns)	Frame $\Delta t$ (ns)	left/right $\Delta t$ (ns)
frame 1	2.0		0.9
frame 2	2.0	4.3	0.8

# Example of Furi flat-field measurement using 600ps pulsed x-ray illumination

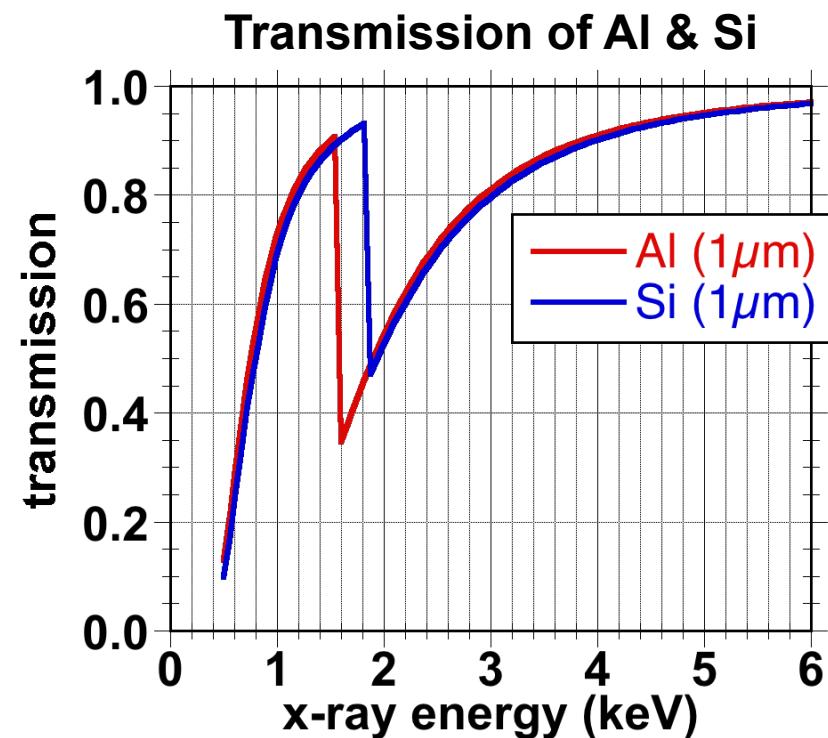
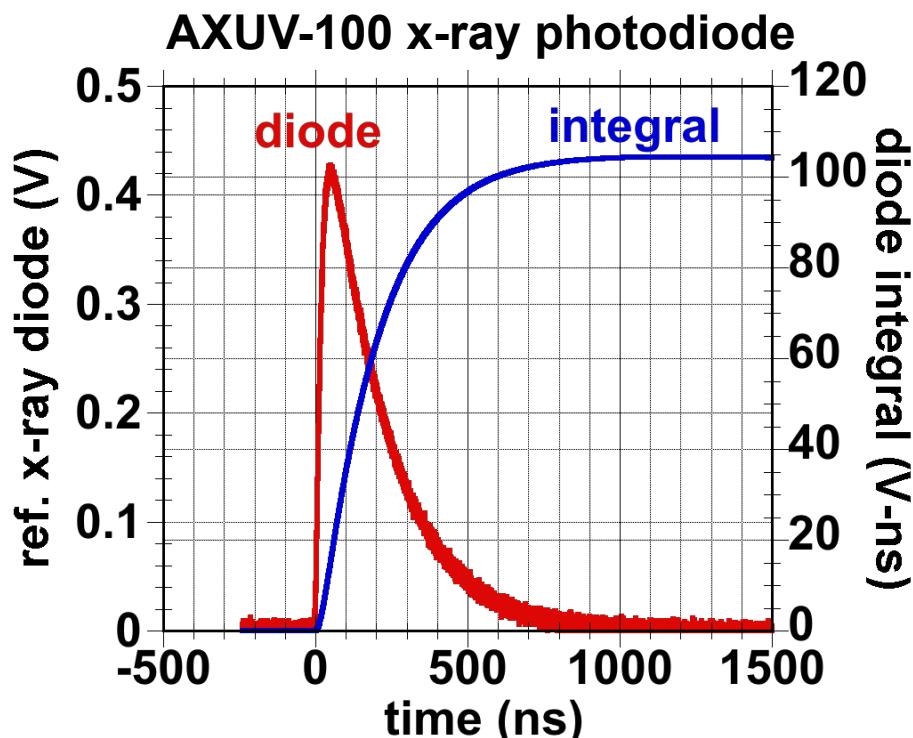
Frame 2, F1X8 sensor  
10/10ns timing mode



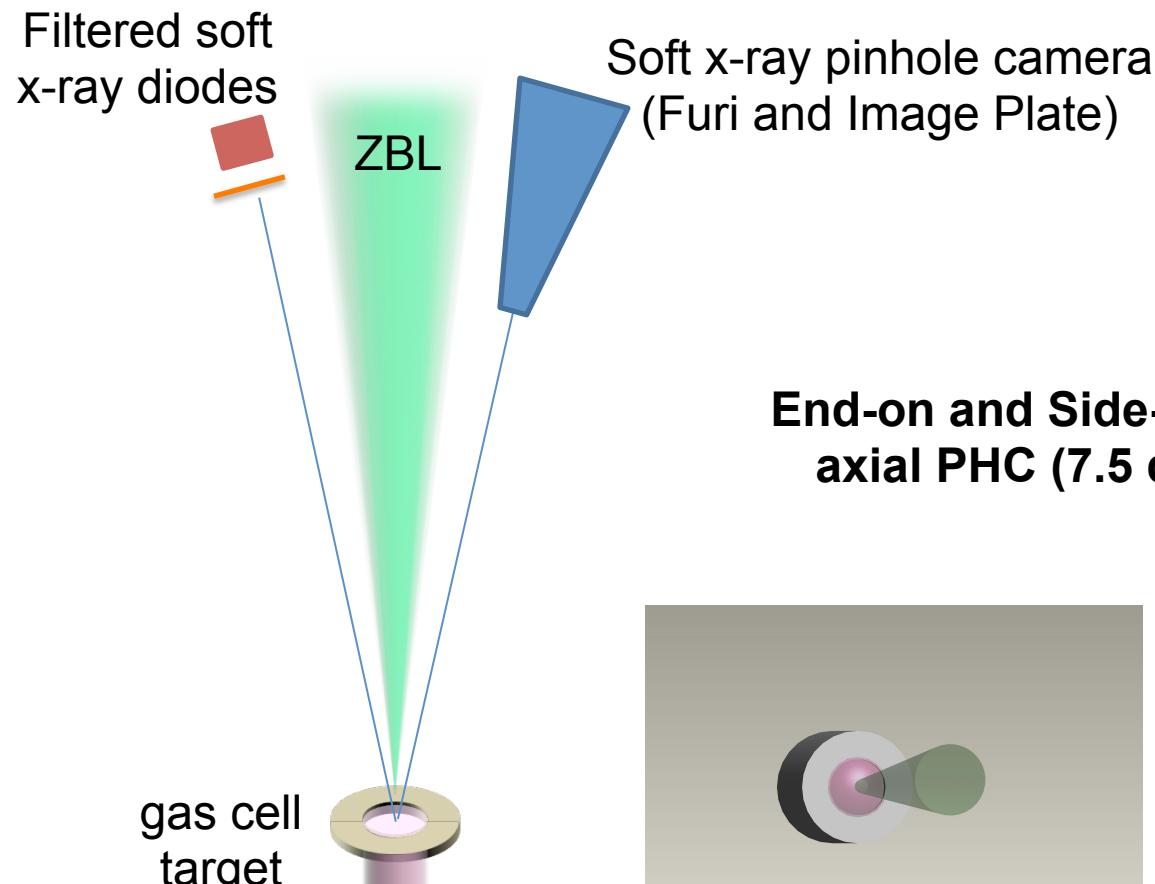
# Cross calibration of x-ray sensitivity using AXUV-100 Si photodiode

Ref. diode model: IRD AXUV-100  
 Ref. diode thickness: 40-50 $\mu\text{m}$   
 Ref. diode aperture: 5 mm dia.  
 Ref. diode sensitivity: 3.62 eV/e-h pair  
 Target/diode distance: 77 cm  
 Target/F1X8 distance: 52 cm  
 X-ray filter: 12.5 $\mu\text{m}$  Al  
 X-ray target material: Mg (1.5 keV x-rays)

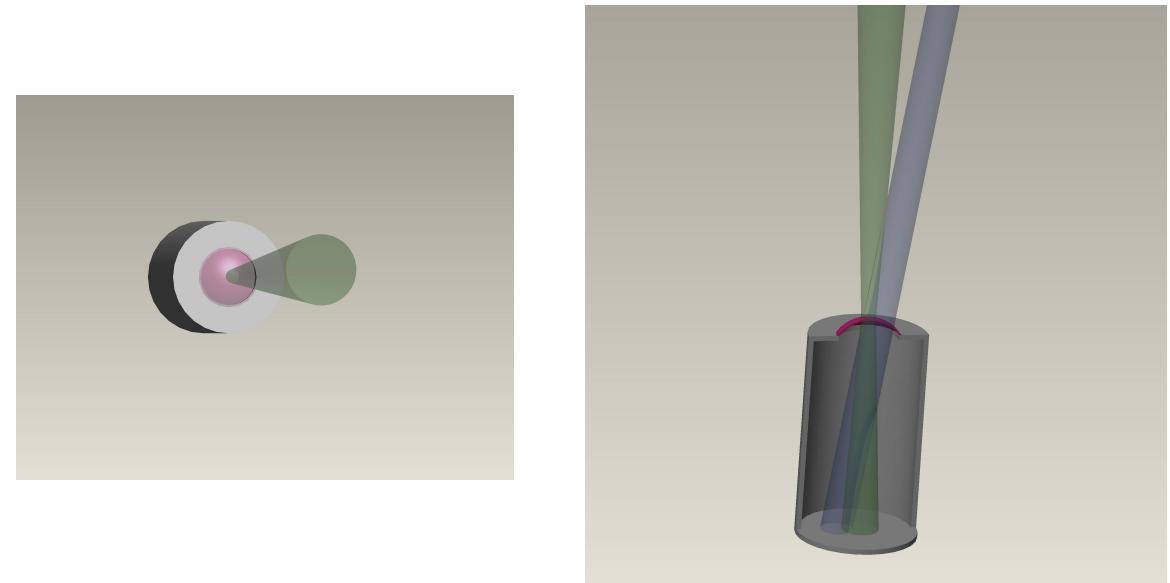
Ref. diode integral into 50 $\Omega$ : 105 V-ns  
 Ref. diode collected charge:  $1.3 \times 10^{10} \text{ e}^-$   
 Ref. diode absorbed energy:  $4.7 \times 10^{10} \text{ eV}$   
 X-ray flux incident on Furi:  $3.2 \times 10^6 \text{ eV/pixel}$   
 Furi average exposure level: 208 mV  
 Furi sensitivity @ 1.5 keV:  $1.5 \times 10^4 \text{ eV/mV}$   
 Furi design sensitivity for 100% absorption:  $6 \times 10^3 \text{ eV/mV}$



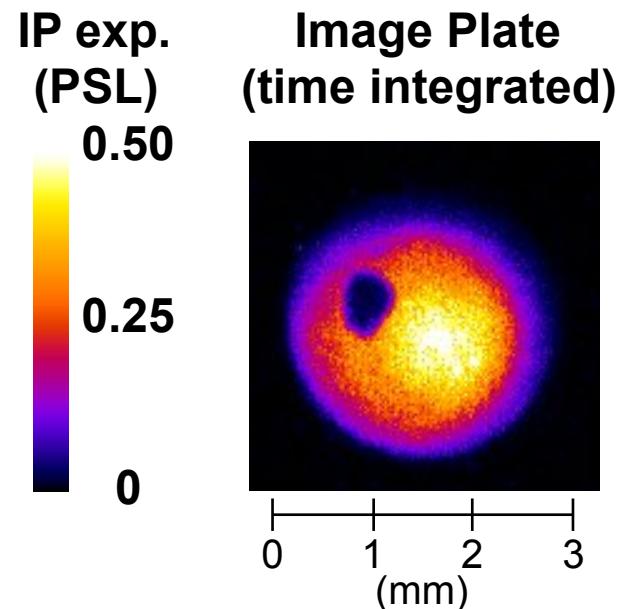
# Experimental setup for axial soft x-ray imaging on Z of Magnitized Liner Inertial Fusion (MagLIF) target



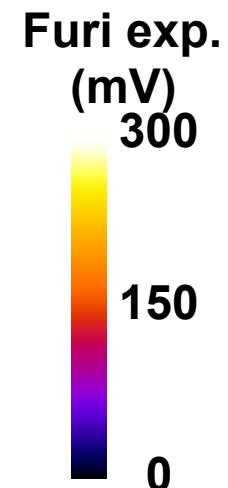
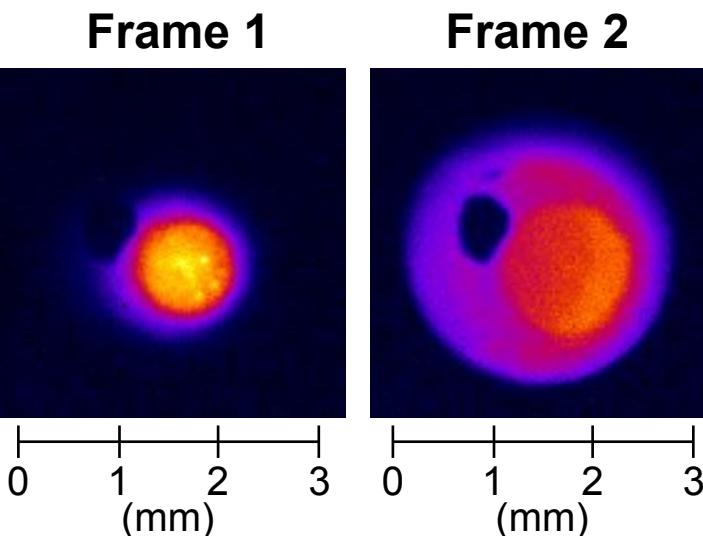
**End-on and Side-on views of target from axial PHC (7.5 degree viewing angle)**



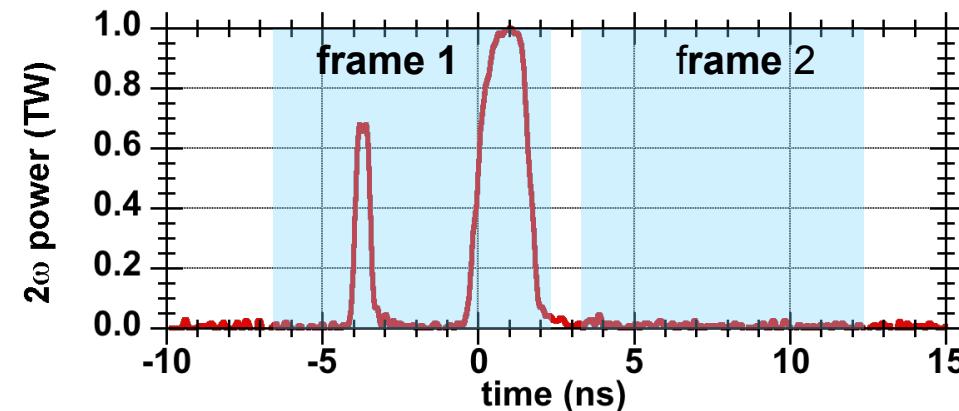
## Axial pinhole camera images on Z shot H33 (6/15/2015)



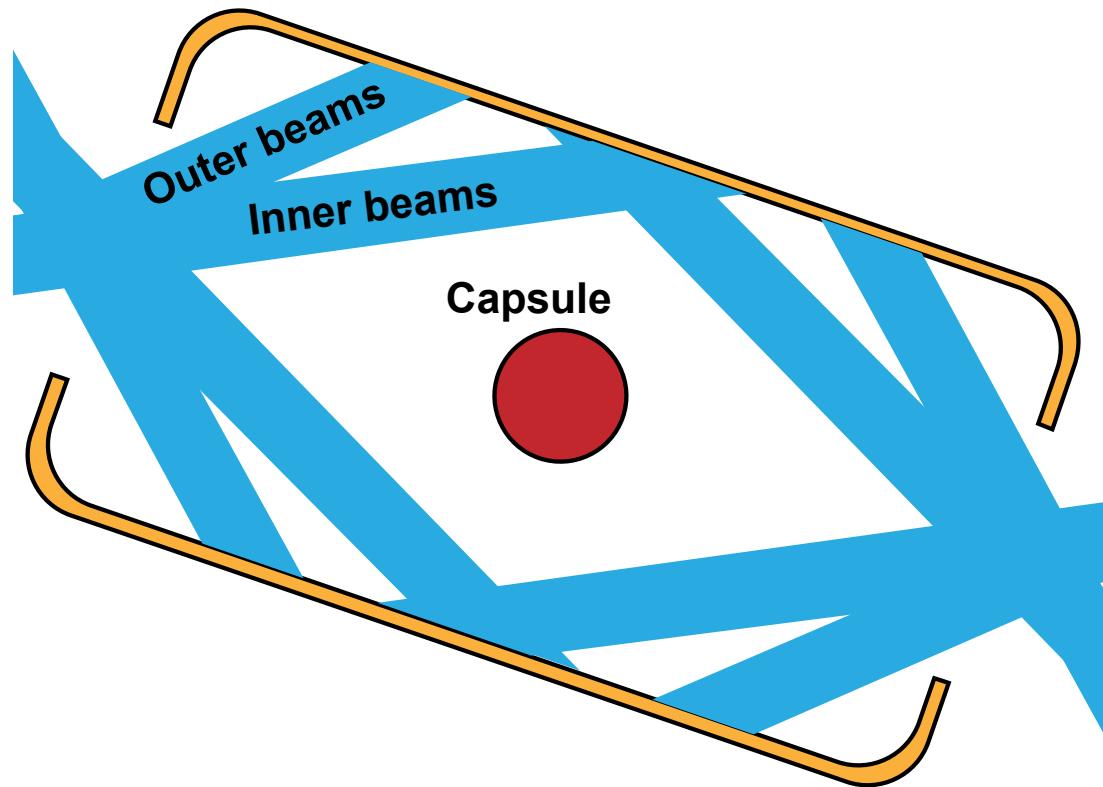
Furi operated in 9ns-on/1ns-off  
timing mode



**Furi timing relative to ZBL laser-heating pulse**

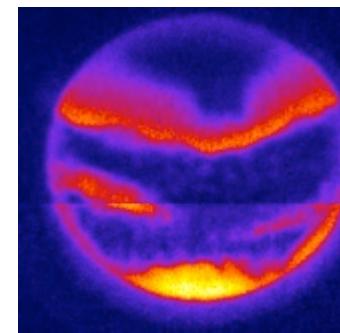


# A Furi camera is being fielded on NIF on the lower SXI diagnostic in place of one of the x-ray CCDs

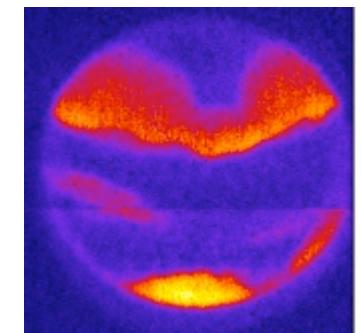


Furi operated in 1ns-on/1ns-off timing mode

Frame 1

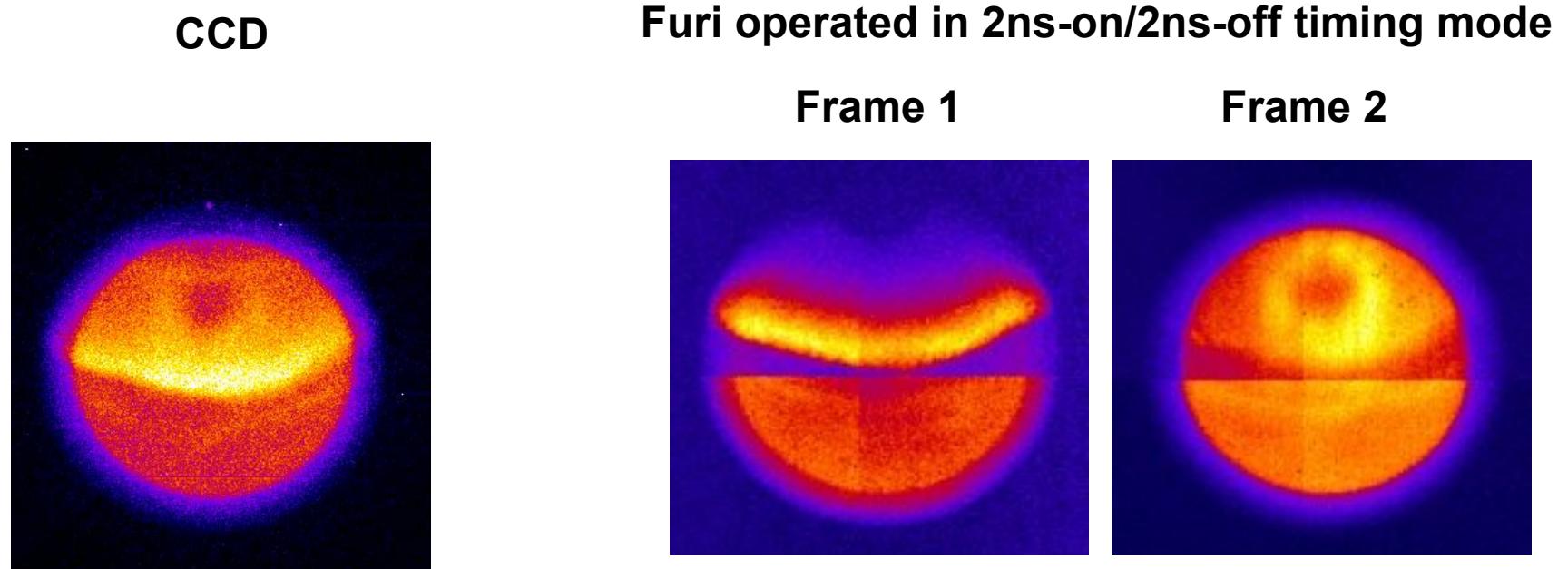


Frame 2



Data courtesy H. Chen and N. Palmer (LLNL)

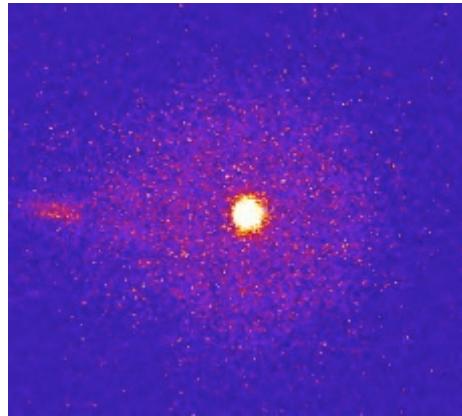
# Comparison of Furi and CCD images on NIF shot N150901-002-999



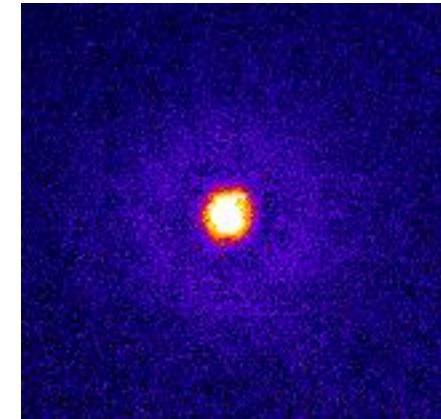
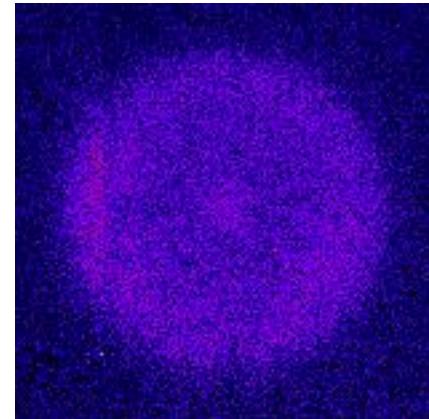
Data courtesy H. Chen and N. Palmer (LLNL)

# Furi images from recent NIF exploding pusher experiment

CCD image from  
a similar shot



Furi operated in 1ns-on/1ns-off timing mode  
Frame 1                                                  Frame 2



Data courtesy H. Chen and N. Palmer (LLNL)

## Next Steps

- **Characterize & begin fielding next-generation cameras**
  - Hippogriff
  - Icarus
  - Small Outline Package
- **Integrate cameras into new diagnostics**
  - Multi-frame x-ray backlighting
  - Pulse-dilation framing camera
  - X-ray spectrometers
  - Visible shadowgraphy
  - Neutron detection
- **Correct limitations in present Furi/Hippogriff design**
  - Improve exposure uniformity
  - Reduce integration time
  - Option for using diodes optimized for higher- or lower-energy detection
  - Option for “tiling” to increase effective sensor size