

***DRACO*—A New Multidimensional Hydrocode**

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A program to develop a new multidimensional hydrocode is underway at LLE. *DRACO* is an arbitrary Lagrange-Eulerian (ALE) code designed to run in 1, 2, and 3 dimensions in planar (cartesian), cylindrical, and spherical geometries. The basic hydroportion of *DRACO* employs second-order rezoning and interface tracking. A mixed-material equation of state (EOS) using *SESAME* or Wisconsin table lookups has recently been incorporated. One of the main objectives of the program is to fully exploit the parallel capabilities of the 32-processor SGI Origin-2000. This paper will describe the basic code, present results of our parallel work, and show results of recent burnthrough calculations. This work was supported by the U.S. Department of Energy Office of Inertial Confinement Fusion under Cooperative Agreement No. DE-FC03-92SF19460, the University of Rochester, and the New York State Energy Research and Development Authority.

—DRACO—

A New Multidimensional Hydrocode

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Abstract

A program to develop a new multidimensional hydrocode is underway at LLE. *DRACO* is an arbitrary Lagrangian–Eulerian (ALE) code designed to run in 1, 2, and 3 dimensions in planar (cartesian), cylindrical, and spherical geometries. The basic hydro portion of *DRACO* employs second-order rezoning and interface tracking. A mixed-material equation of state (EOS) using *SESAME* or Wisconsin table lookup has recently been incorporated. One of the main objectives of the program is to fully exploit the parallel capabilities of the 32-processor SGI Origin-2000. This paper will describe the basic code, present results of our parallel work, and show results of recent burnthrough calculations.

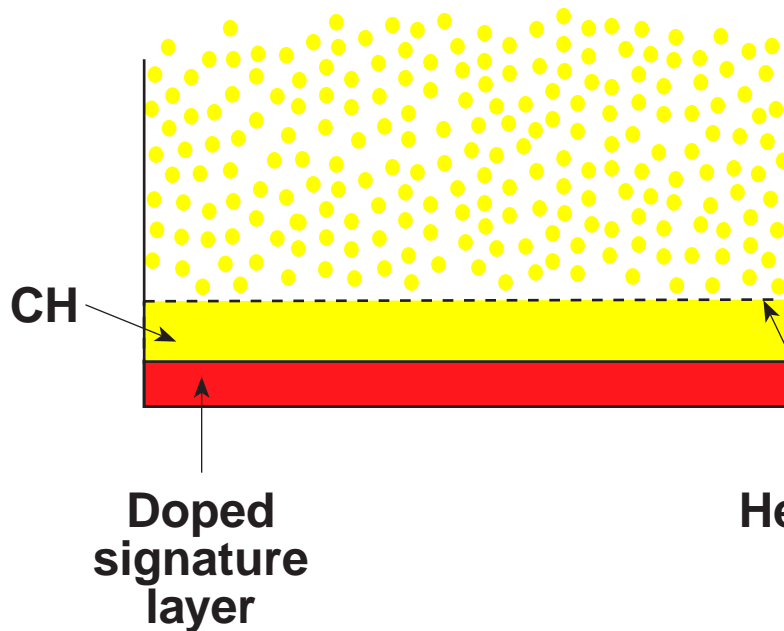
A number of top-level goals have been identified to guide the development of *DRACO*



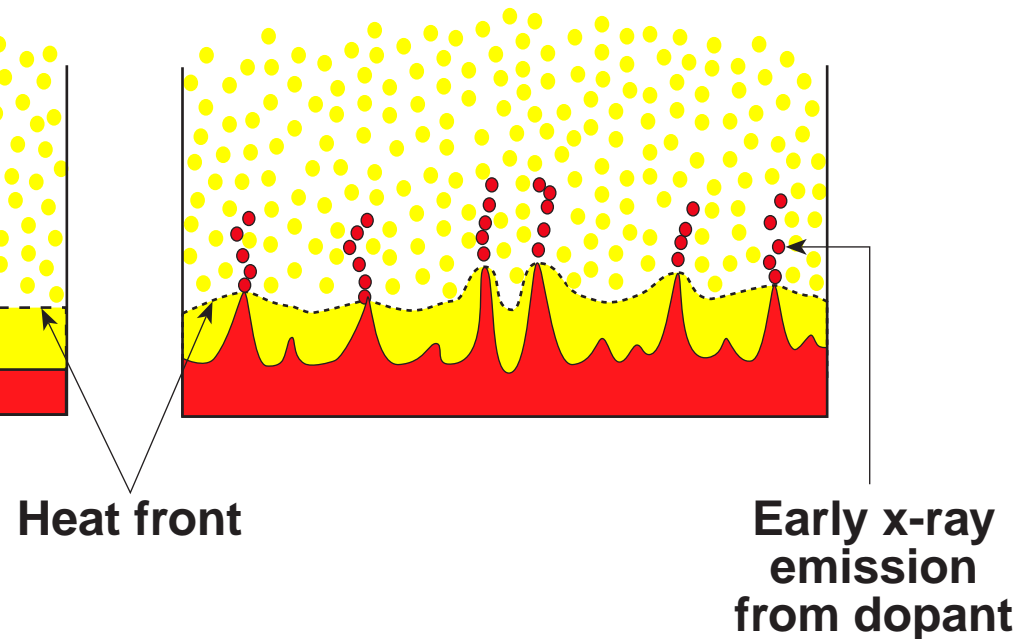
- The goals of this effort are
 - Introduce new and improved algorithms into the code (based on physics requirements and machine/code performance).
 - Develop a code targeted for new multiprocessor machine architectures.
 - Develop a code capable of running 1-D, 2-D, or 3-D using common physics packages and algorithms (where possible).

RT instability growth of accelerating shell has been examined using burnthrough technique

Ideal
one-dimensional case



Nonuniform
drive



***DRACO* is a newly developed hydrodynamics code for direct-drive ICF research**

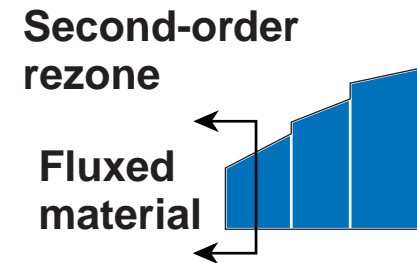
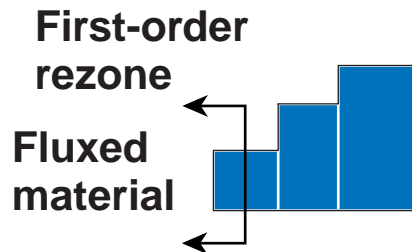


- ***DRACO* uses the ALE (arbitrary Lagrangian–Eulerian) formulation to solve the hydro equations.**
- **Physics modules to enable *DRACO* to simulate planar burnthrough experiments have been added:**
 - **second-order rezoning**
 - **interface tracking**
 - **mixed-material EOS**
 - **laser-energy deposition**
 - **radiation transport**

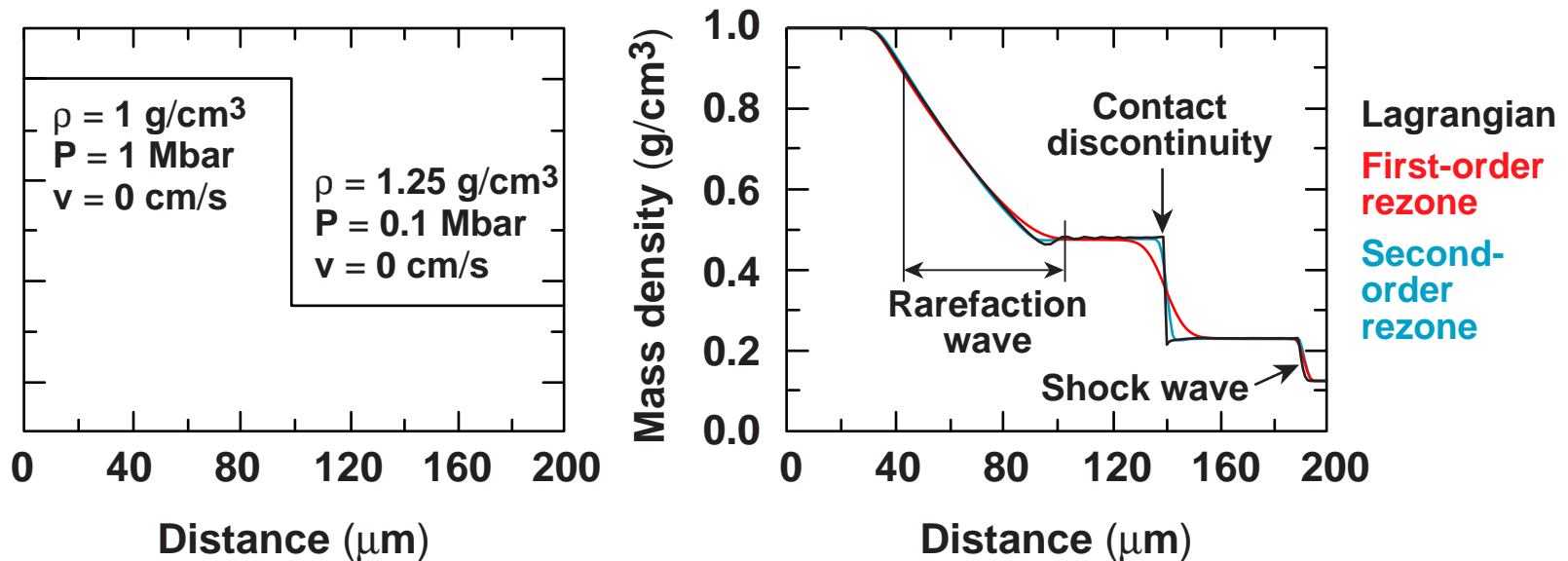
Second-Order Rezoning

Van Leer's method has been added to *DRACO* to give second-order accurate advection

- Van Leer's method takes into account the gradients of the fluxed material necessary to achieve a second-order accurate solution:

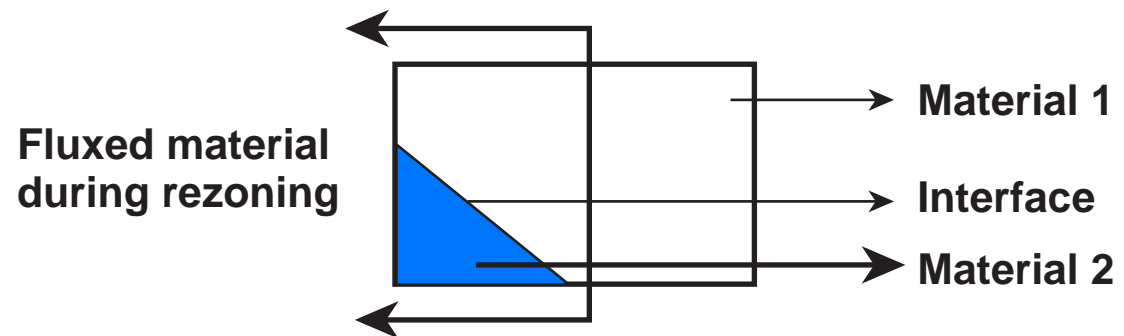


- Van Leer's method captures the position of the contact discontinuity in Sod's problem*.

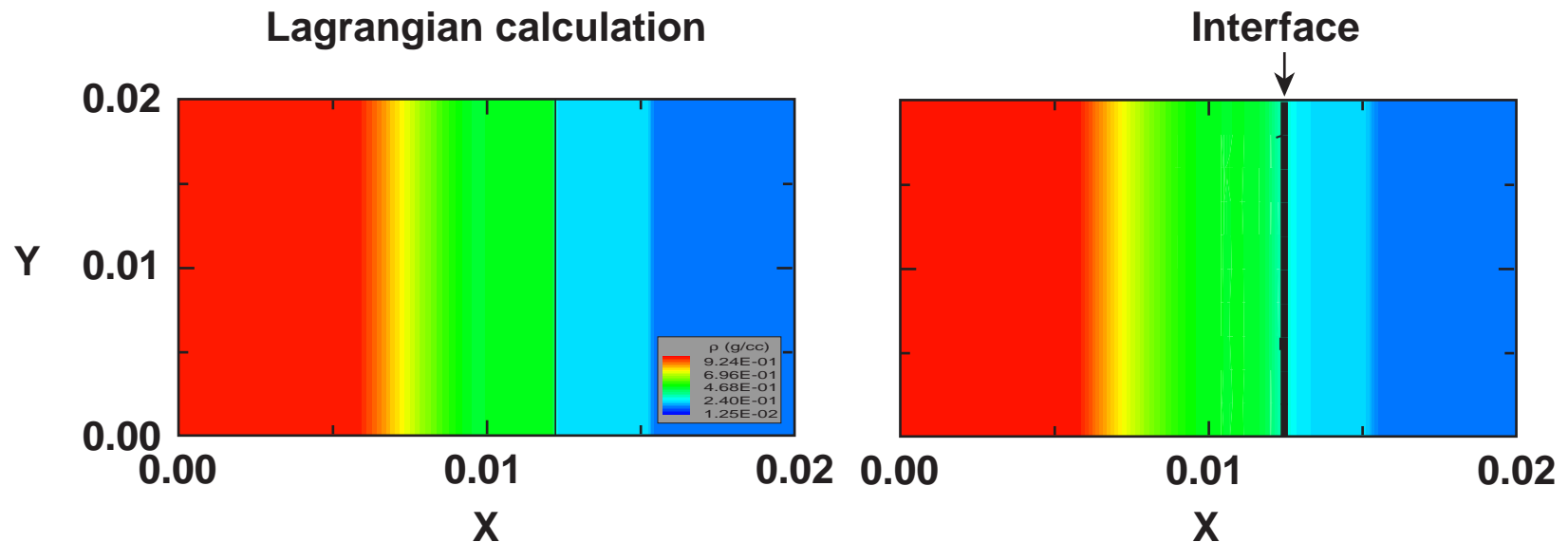


Interfaces between materials can be tracked in *DRACO* using methods based on volume fractions

- Youngs' method* uses the gradient of material volume fraction to draw a straight-line interface in the cell.

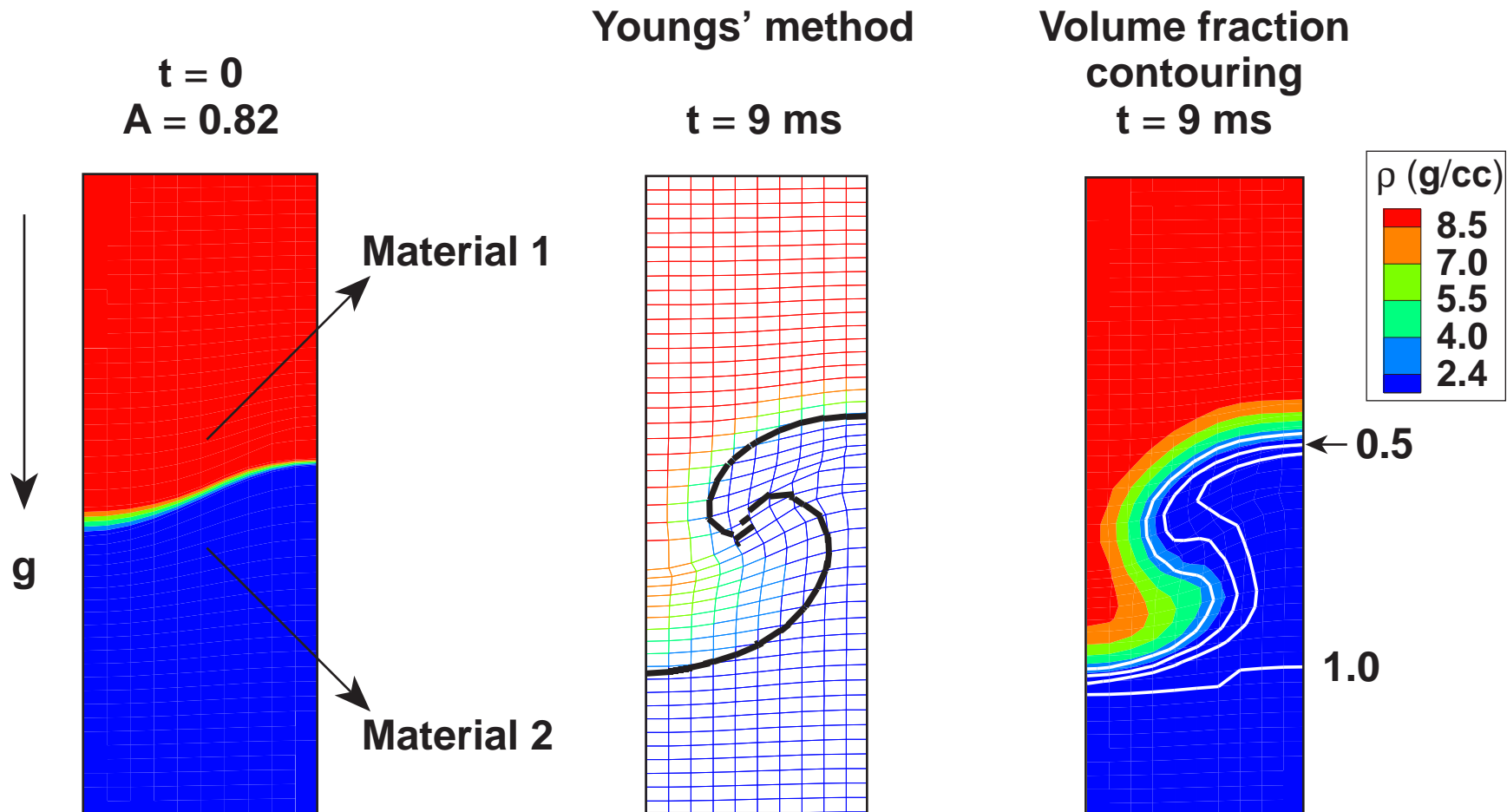


- Sod's problem



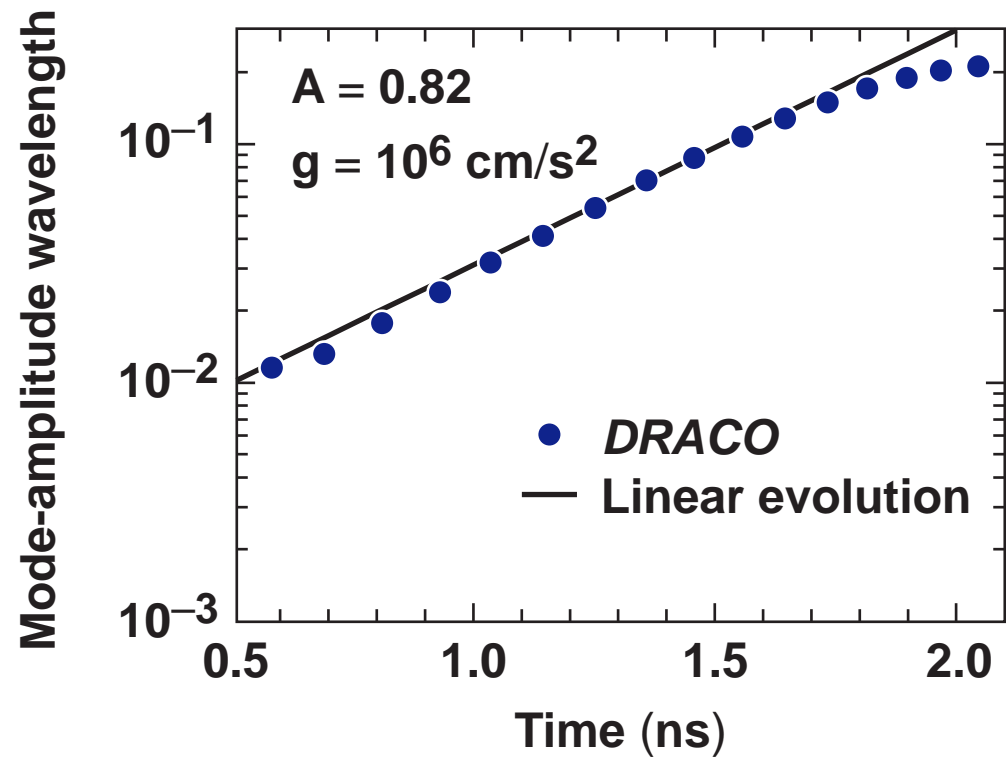
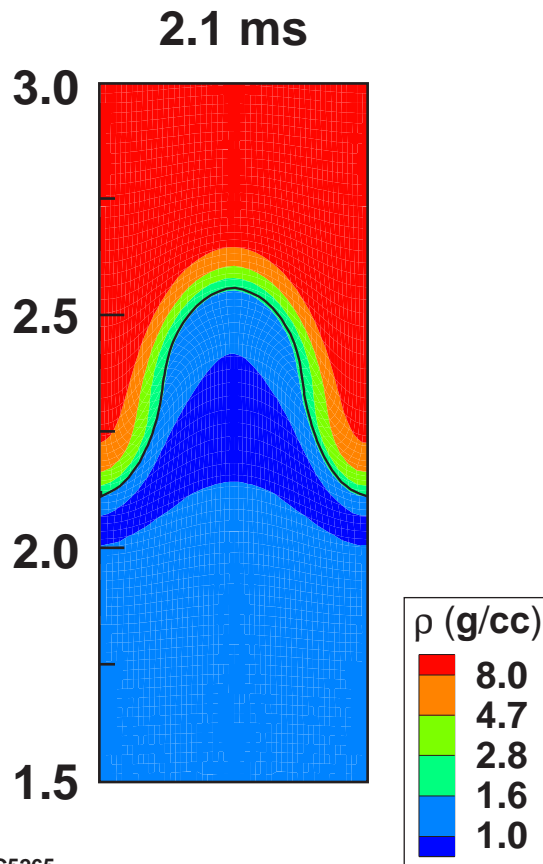
*D. L. Youngs, Physica D 12, 45 (1984).

Interfaces between materials can be tracked in *DRACO* using methods based on volume fractions



Interface tracking in *DRACO* has been tested on a variety of problems

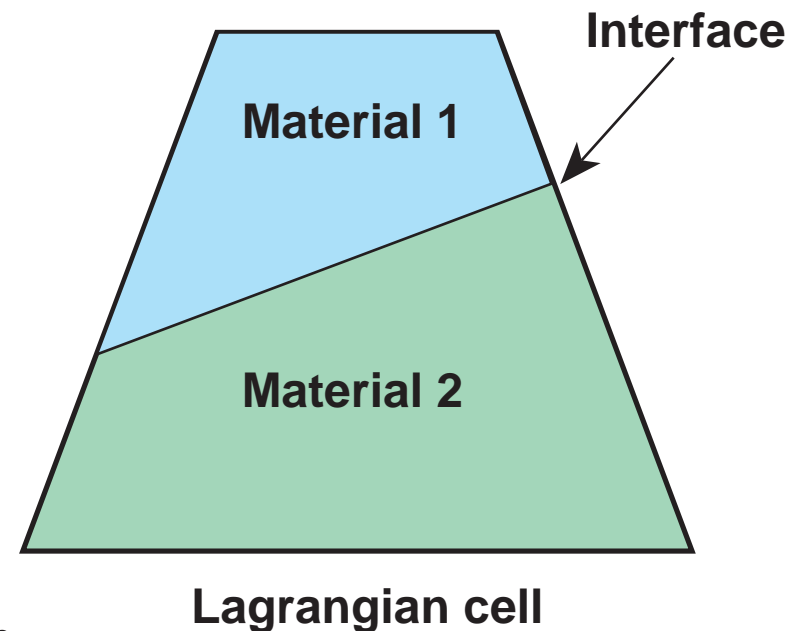
- Classical Rayleigh–Taylor instability



Mixed-material EOS

Mixed-material EOS has been added to enable *DRACO* to track materials

- Supported EOS models:
 - ideal gas
 - perfect gas
 - linearly interpolated EOS table lookup (*SESAME*)
 - Logarithmically interpolated EOS table lookup (*SESAME*)
- Assumptions:
 - thermal equilibrium
 - constant volume fraction
 - Cell pressure is the volume fraction-weighted average of the individual pressures.



In two cases EOS calculation/lookup is required during a timestep

- Following Lagrangian physics:

- known: $T^{i(e)}, f_{vj}, \rho_j$

For logarithmic table lookup, this requires nonlinear, iterative root finding.

- Following rezoning:

- known: $E_{int_{tot}}^{i(e)}, f_{vj}, \rho_j$

- “inverse” calculation/lookup of values for $T^{i(e)}$

- In both cases

- “forward” calculation/lookup of values for $P_j^{i(e)}, E_{int_j}^{i(e)}, c_{vj}^{i(e)}, \frac{\partial P_j^{i(e)}}{\partial T^{i(e)}}$
 - cell-averaged values are calculated for

$$P^{i(e)} = \sum_j P_j^{i(e)} \cdot f_{vj}$$

$$\frac{\partial P^{i(e)}}{\partial T^{i(e)}} = \sum_j \frac{\partial P_j^{i(e)}}{\partial T^{i(e)}} \cdot f_{vj}$$

$$E_{int_{tot}}^{i(e)} = \frac{1}{M_{tot}} \sum_j E_{int_j}^{i(e)} \cdot m_j$$

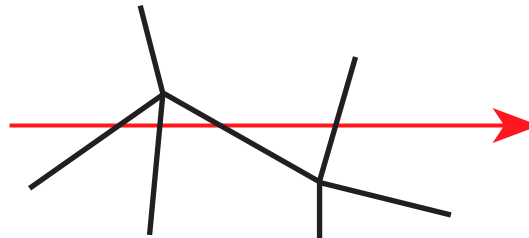
$$c_v^{i(e)} = \frac{1}{m_{tot}} \sum_j c_{vj}^{i(e)} \cdot m_j$$

Laser-energy deposition

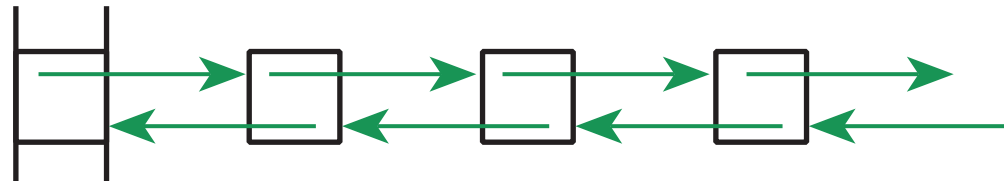
DRACO models inverse-bremsstrahlung laser-energy deposition in one and two dimensions



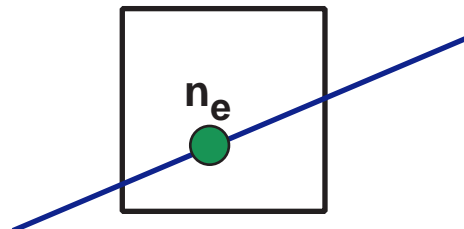
- Ray trace, using direction cosines, determines ray path through distorted mesh.



- Ray paths are stored in an array of doubly linked list, allowing minimal memory use.



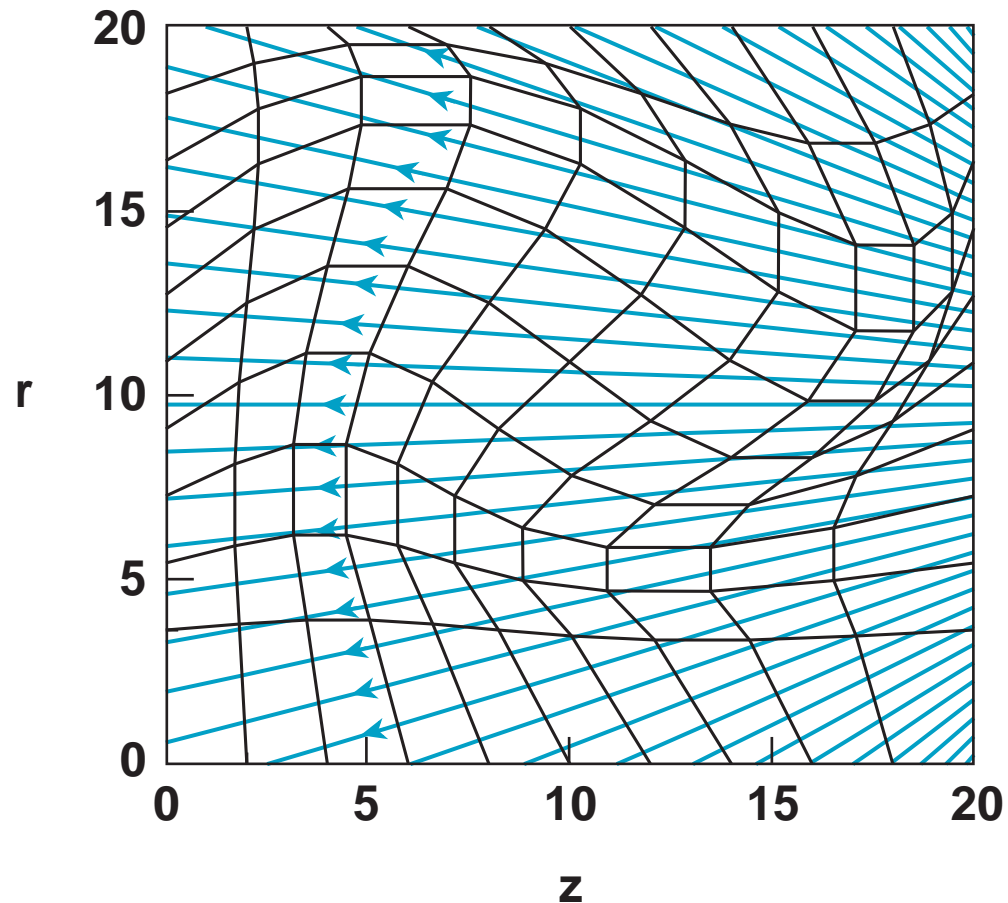
- Given cell-centered electron number densities $[n_e(x)]$ and vertex locations, path-centered and ray/cell-edge $n_e(x)$ values are determined using linear interpolation.



- The Langdon effect to take account of the non-Maxwellian velocity distribution is included.

Normal-incidence ray trace and laser-energy deposition have been tested in 2-D

- 2-D ray trace employs direction cosines.
- Laser energy-deposition has been compared to *LILAC*.



The large number and dynamic nature of global variables require organized maintenance

- ***DRACO* currently has 1122 variables shared via modules (including 717 input variables).**
- **The simultaneous development of new physics modules is constantly adding new controls and simulation features.**
- **Keeping the user and development community informed requires accurate and up-to-date documentation.**
- **Conventional coding requires adding information about a new variable in many places: declaration, initialization, input processing, checkpoint, restart, output, plotting, etc.**

A data structure of attribute information about each global variable is maintained in a linked list

Variable attribute

Record

Name
description
usage
version
module defined
input status
allocation status
namelist
...

Code snippet

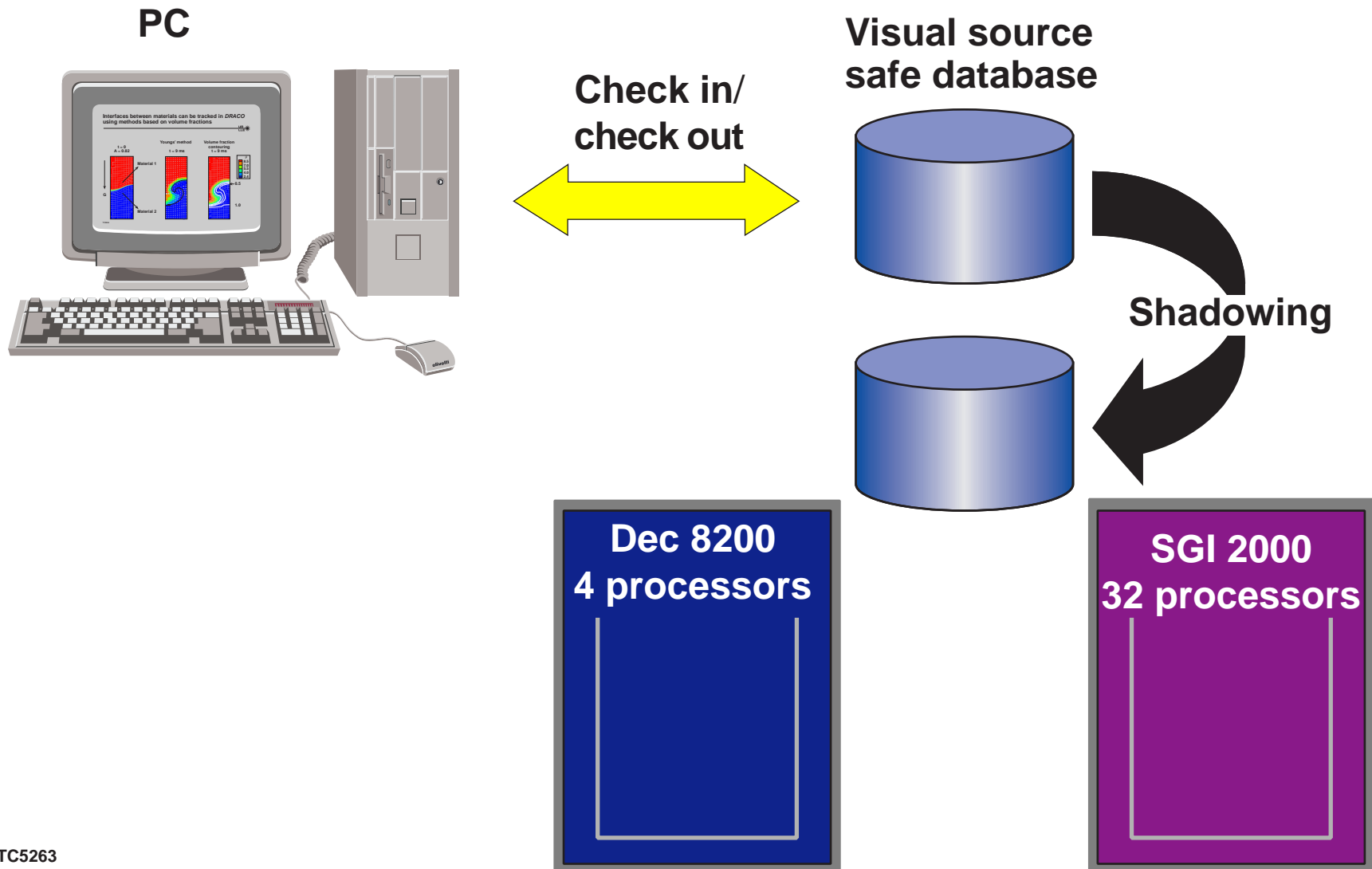
```
...  
do while (associated(g_var))  
  if (g_var%usage/= 'constant') then  
    call write_ckpnt_record(g_var)  
  endif  
  g_var => g_var%next  
enddo  
...
```

- **New variables automatically included throughout the code based on attributes defined in a single instance results in easier maintenance.**

Maintaining attributes about variables has many advantages

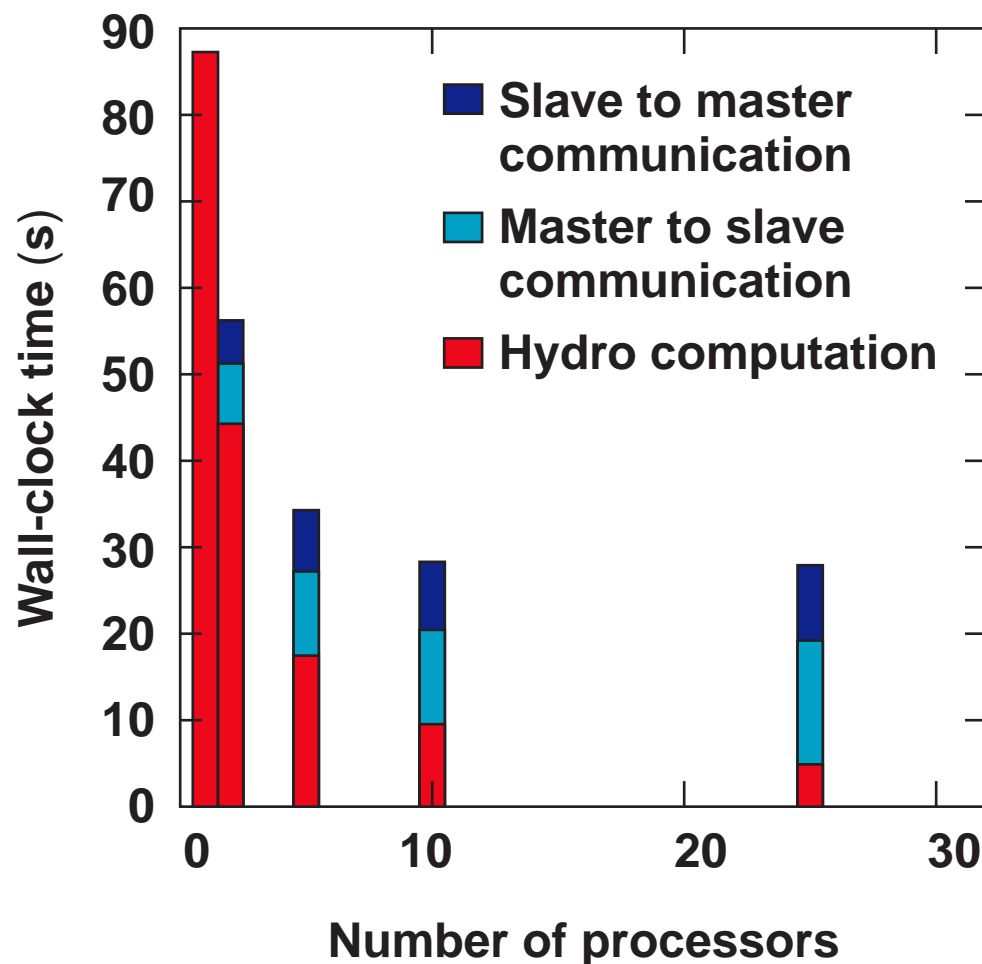
- All attribute information is recorded in a single place.
- Variables are automatically included in code loops where the defined “usage” attribute of the variable applies.
- At least some minimal variable usage is documented in the description field.
- All attributes are automatically formatted into a help file.
- Unique global variable names are guaranteed.

DRACO coding environment uses state-of-the-art software tools for cross-platform development



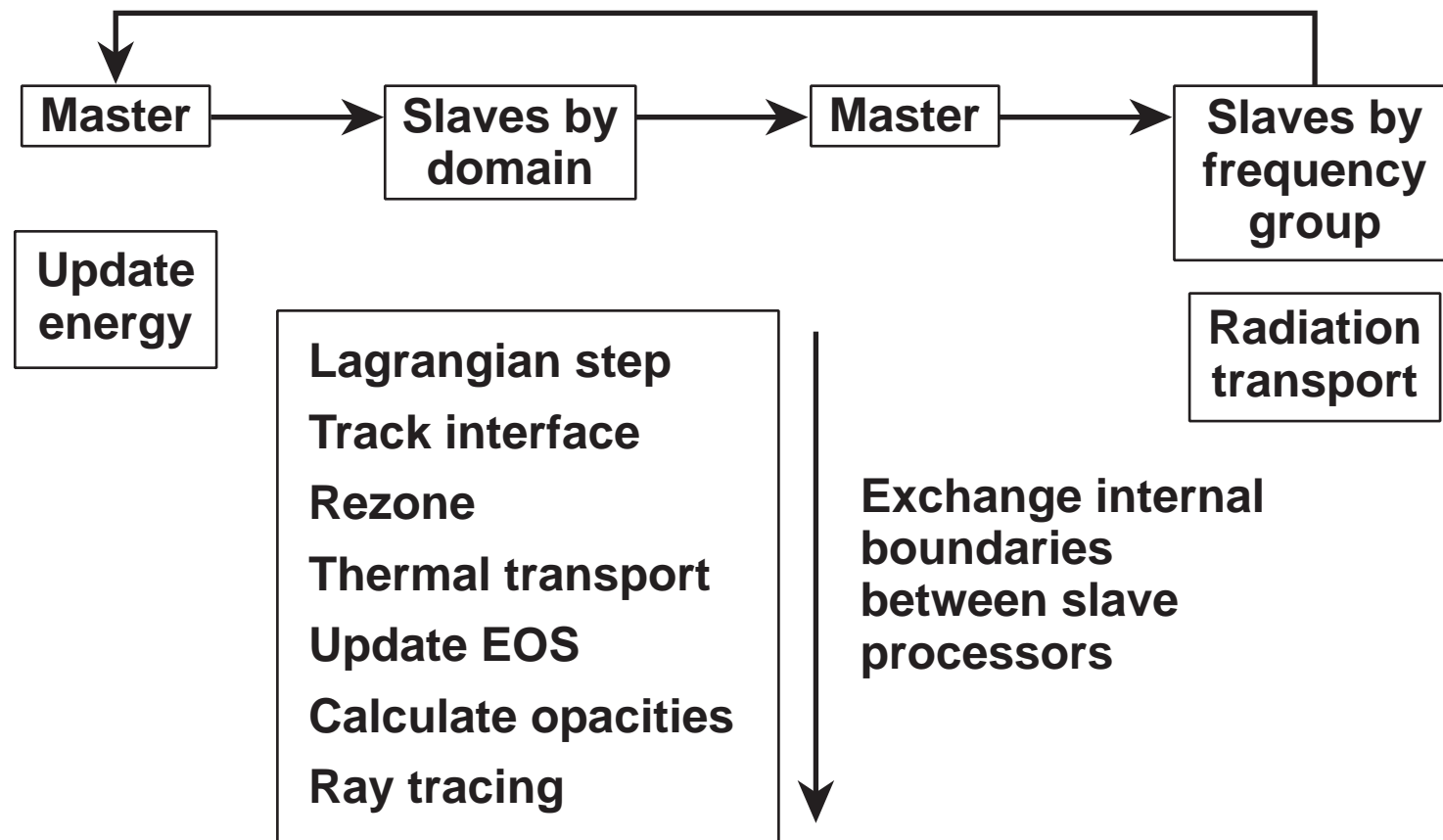
For efficient parallelization, the communication costs must be minimized

- A 400×200 hydrodynamic problem shows almost perfect parallelization of the computational portion.



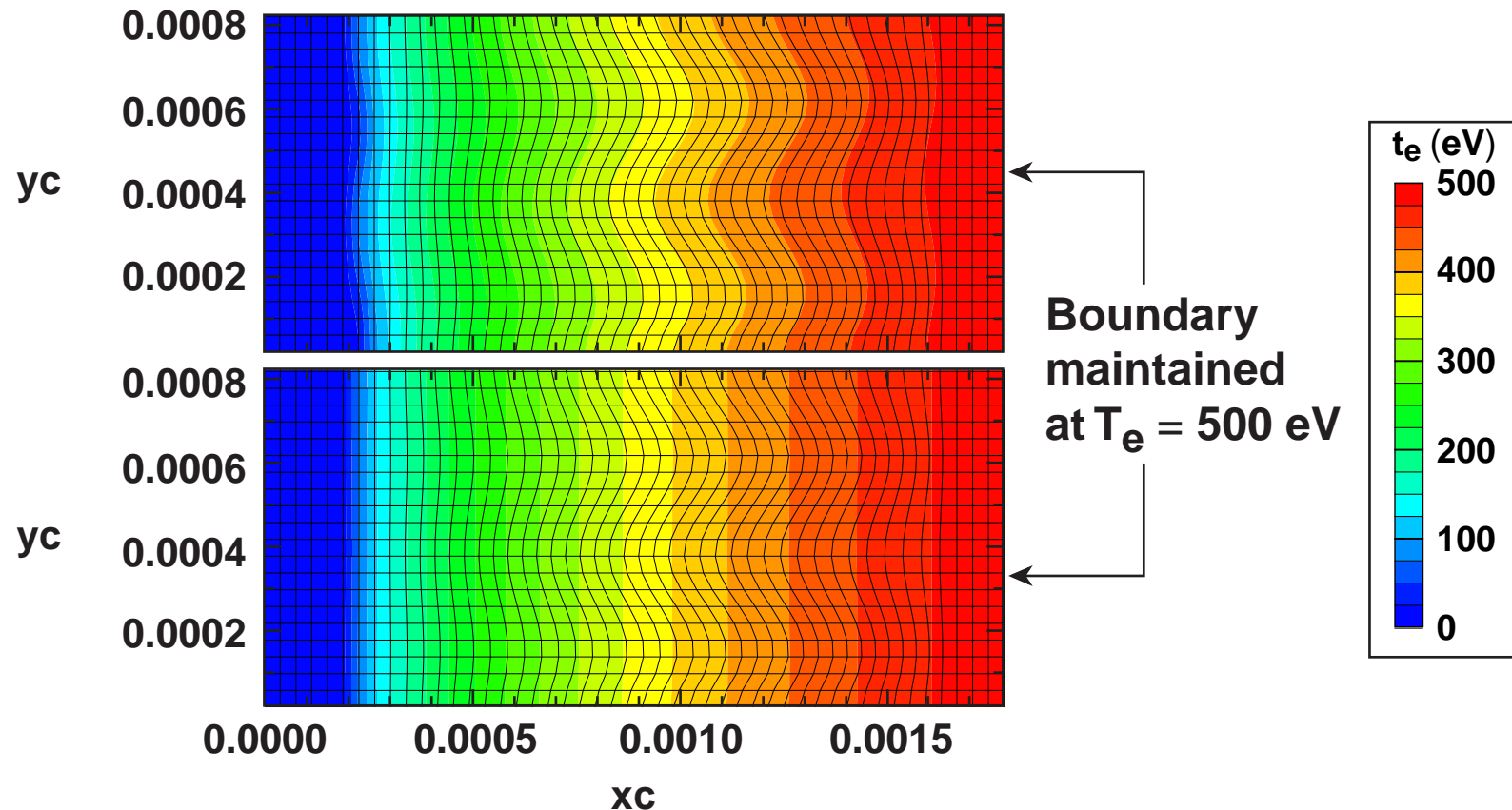
Parallelization will use a mixture of domain decomposition and the master-slave approach

- LLE's work on parallelization to date has shown that it is essential to minimize the communication costs and maximize the computational work.



Maintaining a planar thermal wave through a Lagrangian grid requires a nine-point differencing scheme

- Five-point differencing scheme shows perturbed temperature front.

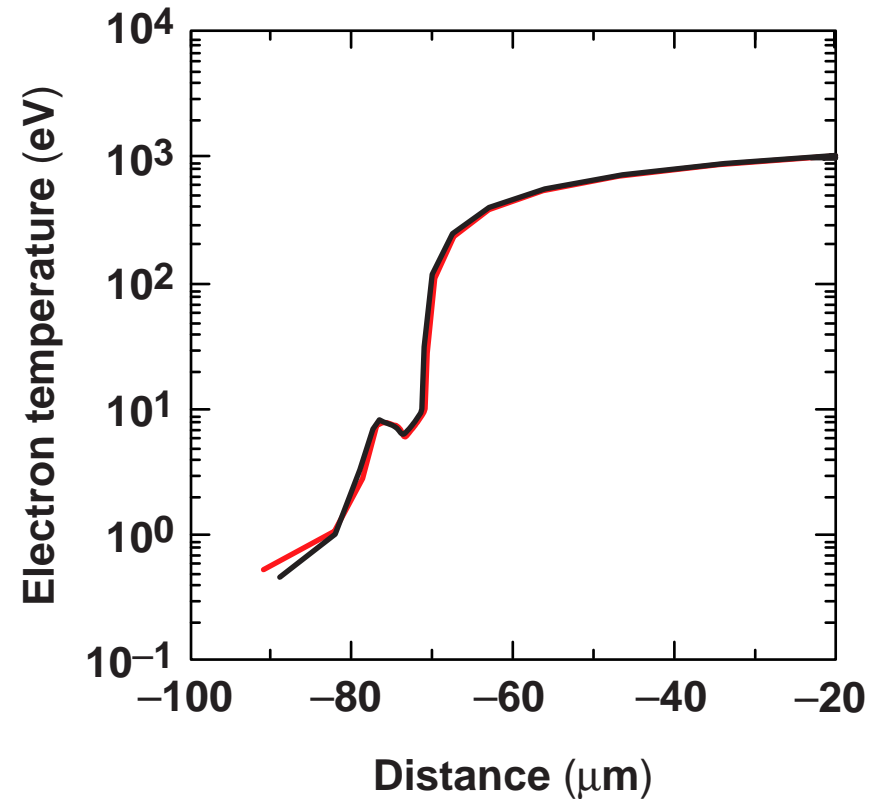
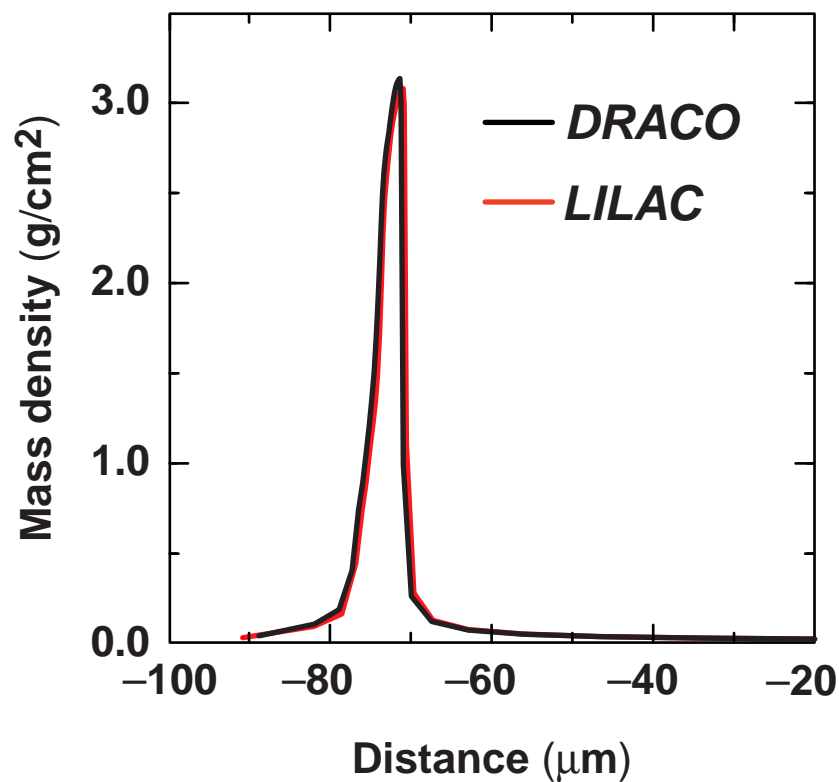


- Nine-point differencing scheme maintains a planar wave.

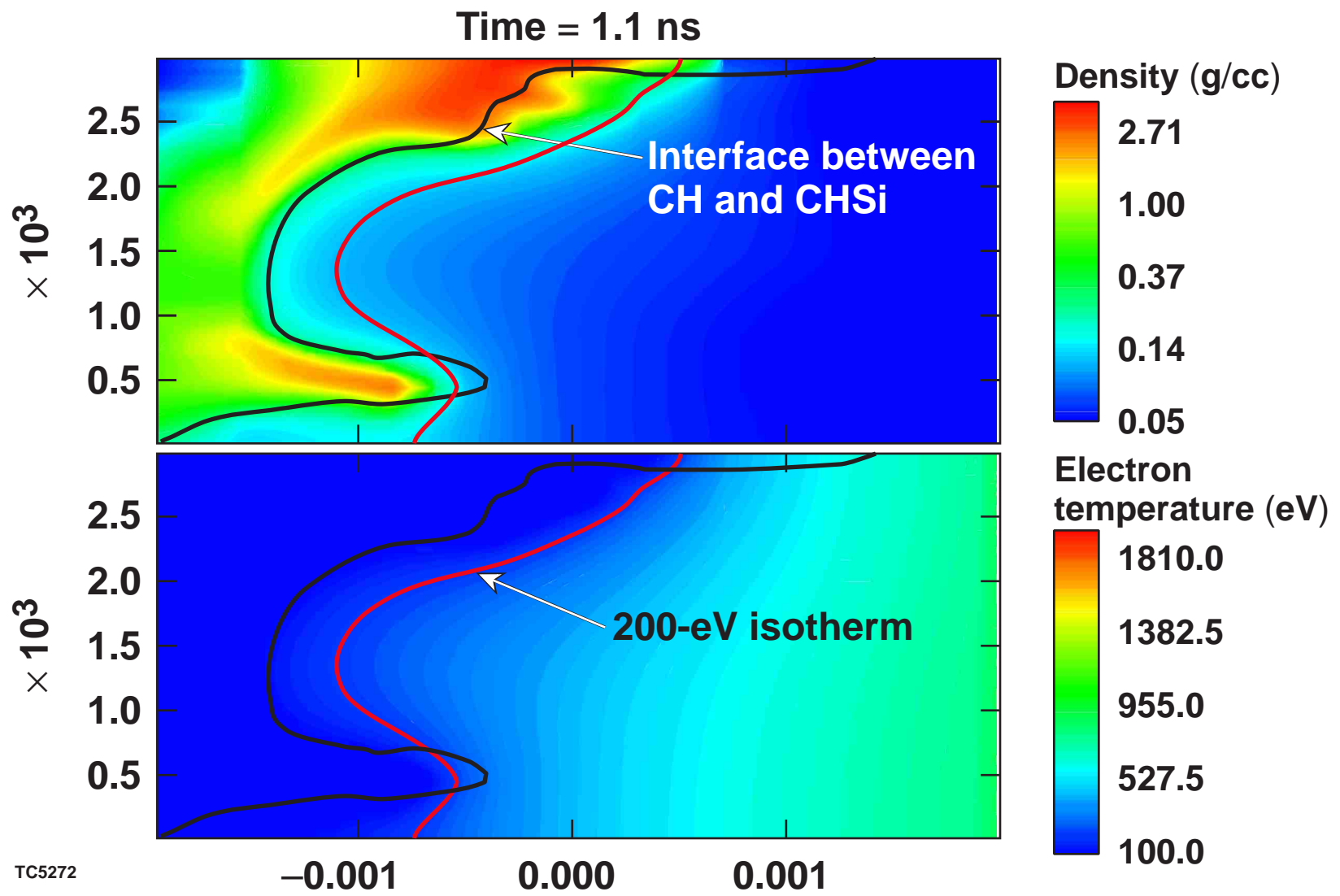
DRACO shows good agreement with LILAC calculations

- A 20- μm planar CH foil is accelerated by a 2-ns flat-top laser pulse with an intensity of $2 \times 10^{14} \text{ W/cm}^2$.

Time = 1.0 ns



A multimode nonuniform laser beam shows burnthrough at the tips of the spikes



Summary

Future work on *DRACO* will include a detailed comparison to experimental and investigations of direct-drive ignition designs



- Comparisons with planar-foil experiments will include
 - effect of laser imprint
 - Rayleigh—Taylor growth of single modes
 - burnthrough event
- Additional physics modules to be added include
 - alpha-particle transport and burn
- Comparisons with implosion experiments will include
 - yields from gas-filled CH shells and CD buried layers
 - emission from buried Ti layers
- Work will continue on parallelization techniques.