### **Update on the Rochester Optical Streak System**





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# The ROSS camera is a comprehensive diagnostic system with autofocusing and self-calibration capability

- The high-precision measurements demanded by the LLE experimental program require precise setup and calibration of the diagnostics.
- The optical calibration module incorporates an extensive imaging, flat-field correction, geometric-distortion, and time-calibration capability.
- All functions can be accessed and monitored remotely.

### All pixels in the recorded image were not created equal

- The system response is dependent on the spatial and temporal position and the focusing conditions.
- To make pretty pictures and FWHM measurements requires minimal calibration.
- Serious quantitative measurements (SNR > 10, DR > 10, nonlinearity < 10%) require extensive calibrations.</li>
- These issues are addressed in the ROSS design with the optical calibration module (OCM).

### The input imaging system is an Offner triplet with motorized controls for the dual object planes and the secondary mirror



#### Flat-fielding a CCD recording system elevates its performance to a near-quantum-limited detector

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## The ROSS–OCM design uses an LED, homogenizer, and a slow ramp to flat-field the system

- Input optics, photocathode quantum efficiency, photoelectron transport, phosphor-conversion efficiency, fiber-optic coupling, and CCD quantum efficiency are all independent of the signal level.
- Uses a 1- to 10-s duration ramp to simplify the illuminationsource design.
- Multiple-wavelength CW–LED's are available internally, or white light passed through an interference filter can be fed in via fiber optics.
- Homogenizer output is spatially uniform to 0.25%.

## Geometric distortions result from electron-optic aberrations and mechanical misalignments

• Manufacturers of streak tubes are reluctant to address these issues—\$\$

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- Use ROSS–OCM flat-field subsystem plus spatial and temporal modulation to produce raw uncorrected images
- $S(x,y) = Jacobian(x,y,x^,y^) \times S(x^,y^), x = U(x^,y^) and y = (x^,y^)$



## Time calibration is accomplished with an on-board, 664-nm, 3-GHz comb generator

- Verify system operation prior to shot
- External source may also be coupled into any or all channels

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### The autofocus capability allows local optimization of the spatial or temporal

Geometric distortion image shows the main EO aberration is field curvature.

Annulus is the intersection of a curved image plane with a flat screen







## The P820 streak tube provides a 2-ps time resolution capability for OMEGA EP diagnostics



• The peak current handling capability is 1.8 mA.

E14133

Summary/Conclusions

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