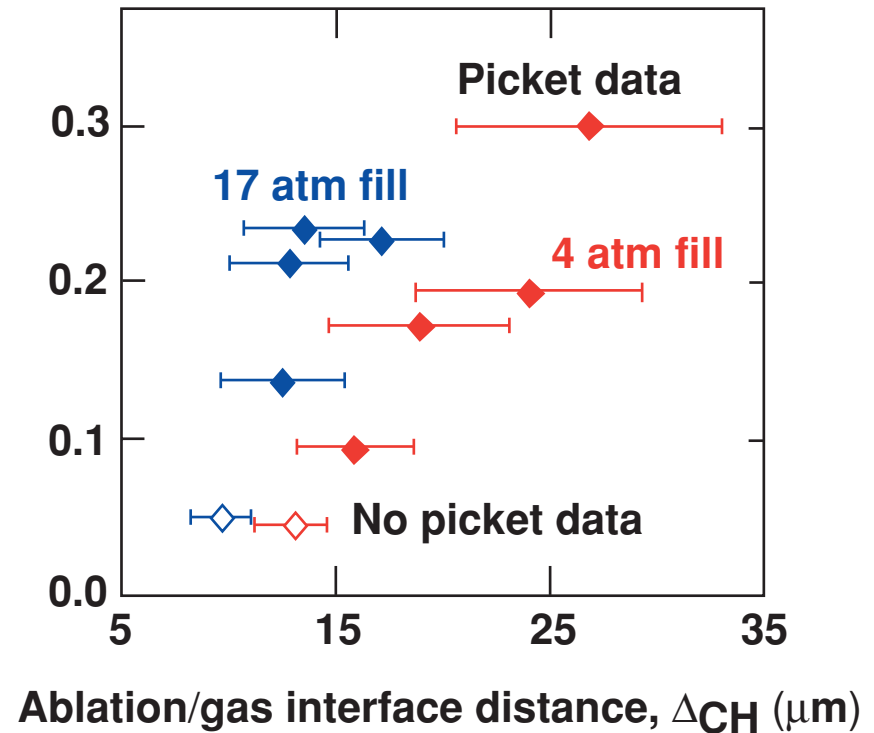
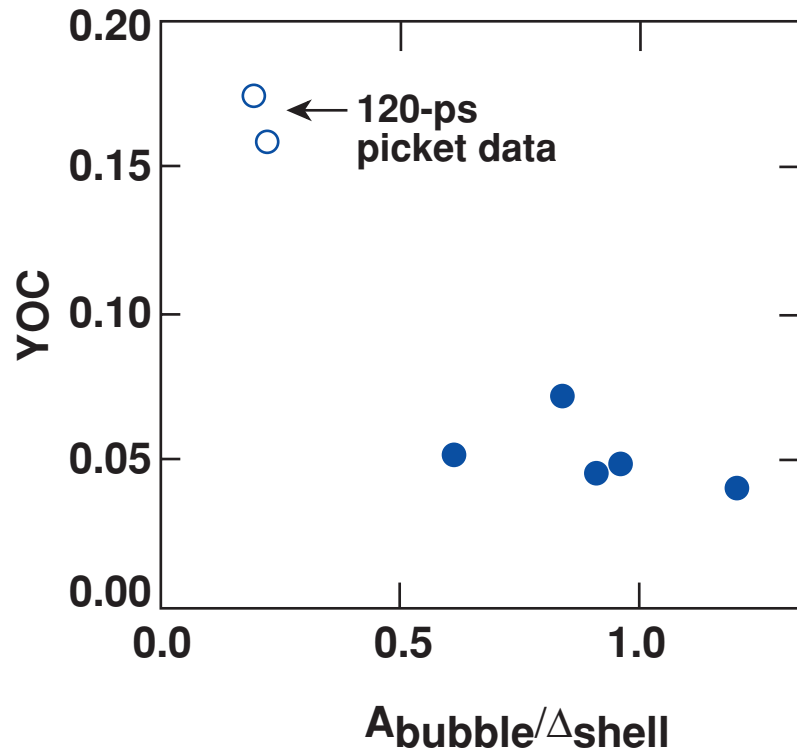


# Direct-Drive ICF Implosions with Picket-Fence Pulse Shapes



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# Collaborators

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## Summary

# Shaped pulses have been used to control the seed amplitude of the deceleration-phase instability

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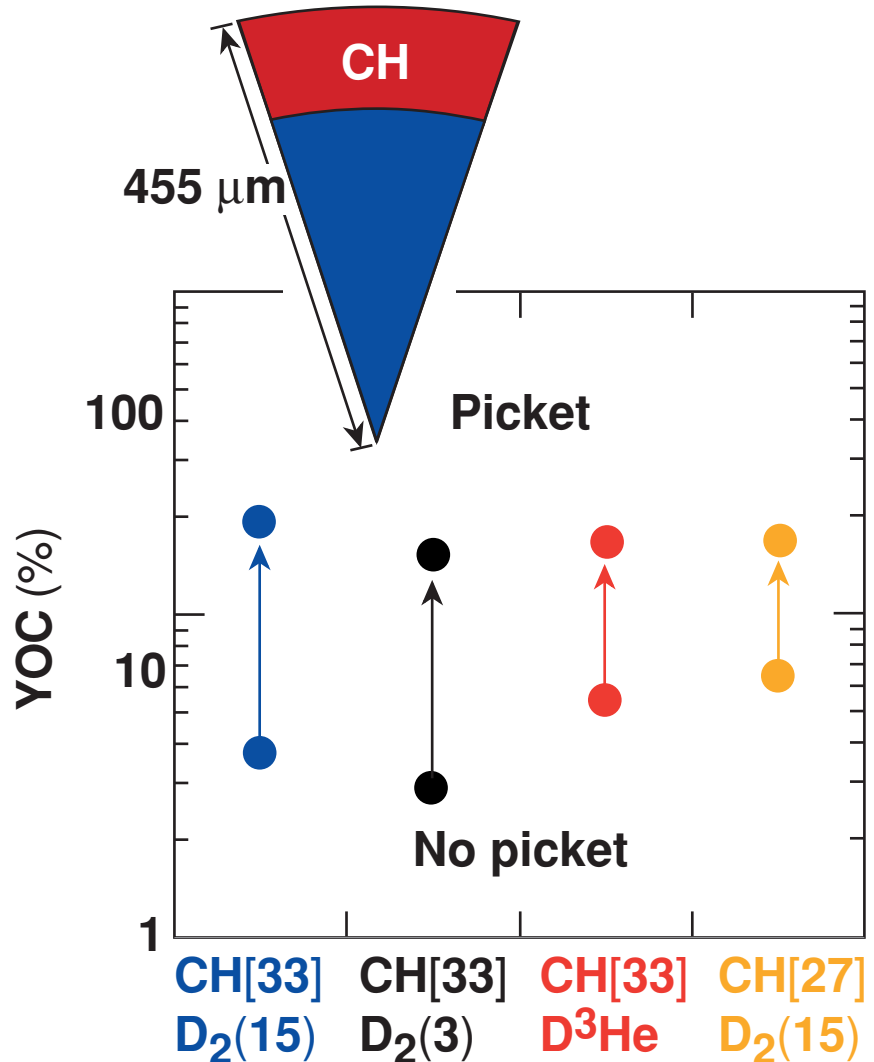
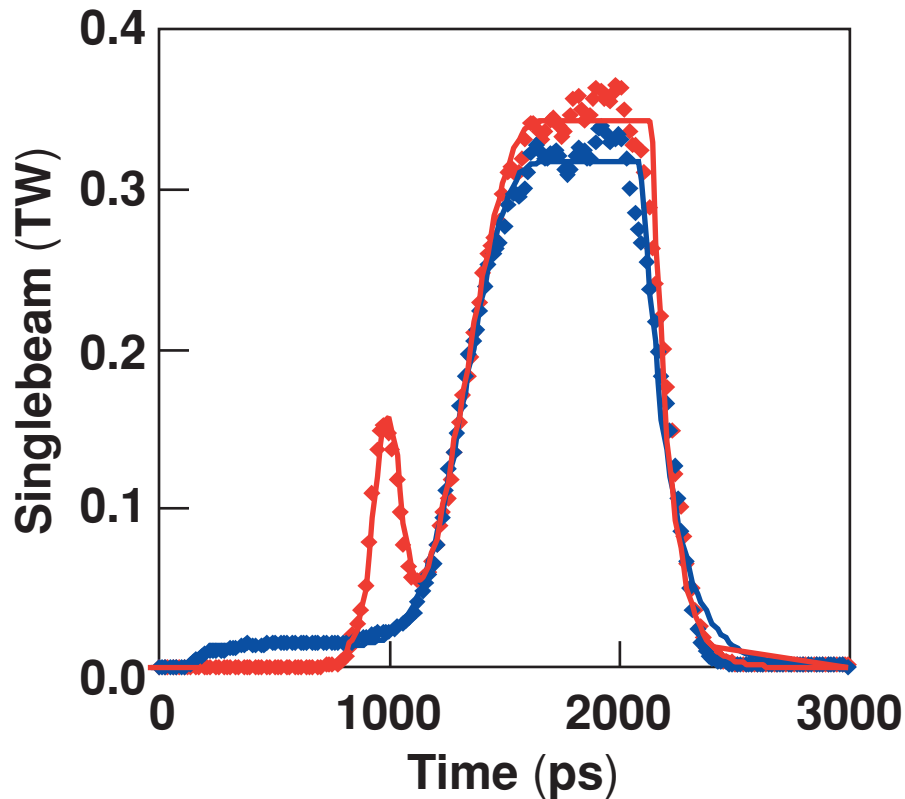


- **First experiments showed significant increase in neutron yield with a picket pulse due to reduction of the deceleration-phase instability initial amplitude.**
- **Experimental yield/1-D simulation yield (YOC) increases with greater separation between the ablation and gas interfaces.**
- **YOC also improves when ablation interface growth is reduced.**

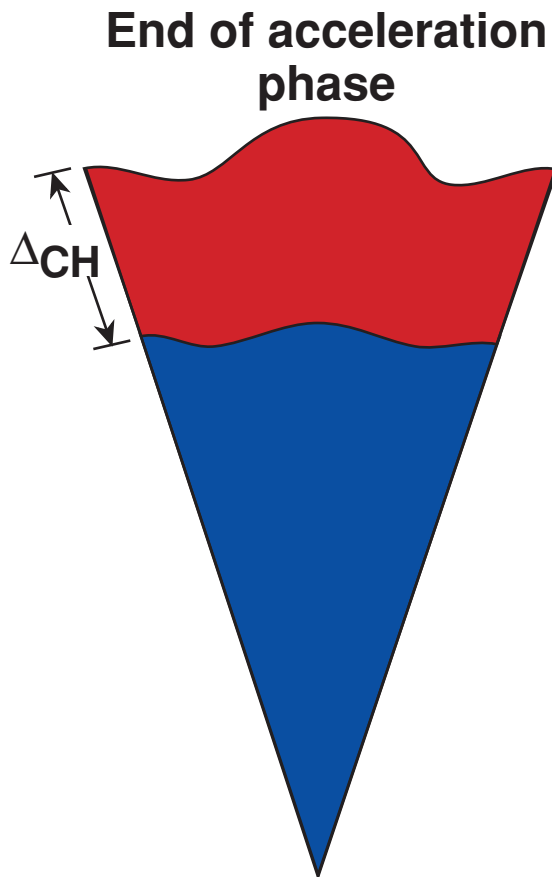
# A 120-ps FWHM picket pulse before the drive pulse showed increased fusion yields

## Picket pulse

Width (FWHM) = 120 ps  
 Amplitude = 0.4 of drive  
 Position = 340 ps before drive



# The Rayleigh–Taylor instability at the shell–gas interface during deceleration strongly affects fusion yield



- Deceleration interface is classically unstable.

$$A = A_{\text{initial}} e^{\gamma t}$$

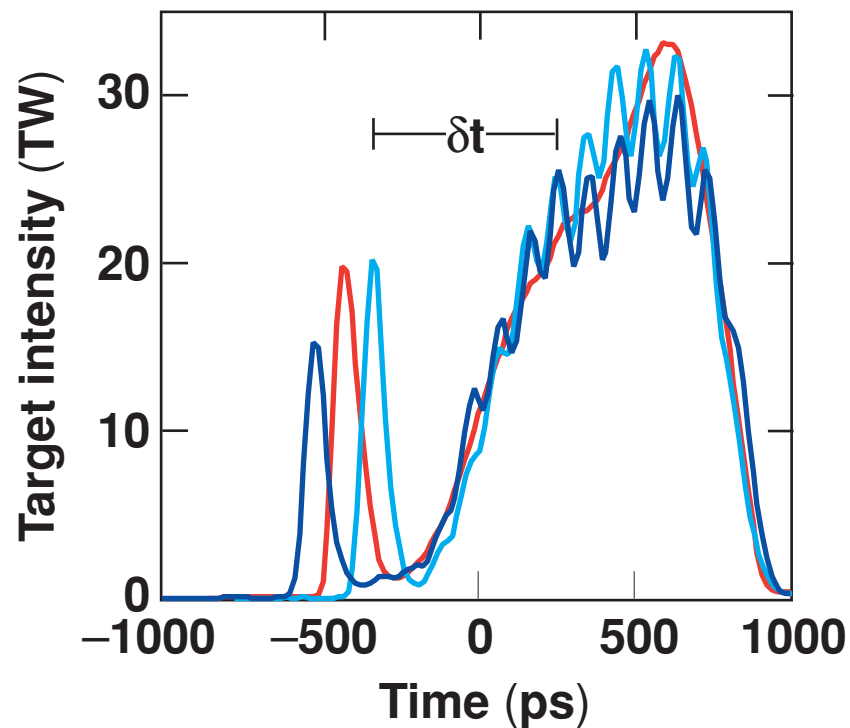
$$A_{\text{initial}} = \sqrt{(A_{\text{inner}}^2 + A_{\text{feedthrough}}^2)}$$

$$A_{\text{feedthrough}} = A_{\text{ablation}} e^{-k\Delta_{CH}}$$

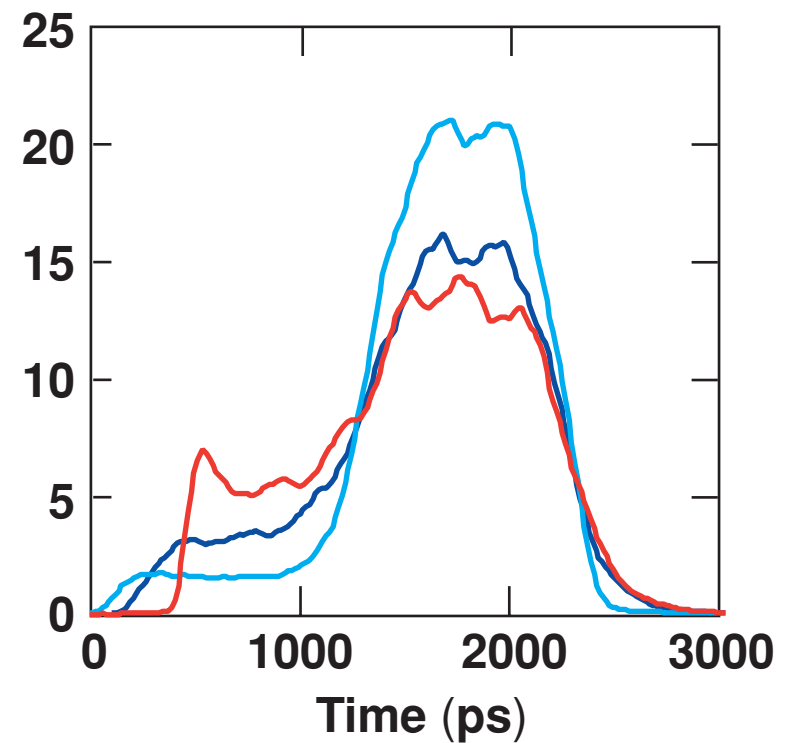
- Shaped-pulse implosions will study both  $A_{\text{ablation}}$  and  $\Delta_{CH}$ .

# CH targets were imploded using laser pulse shapes with and without picket pulses

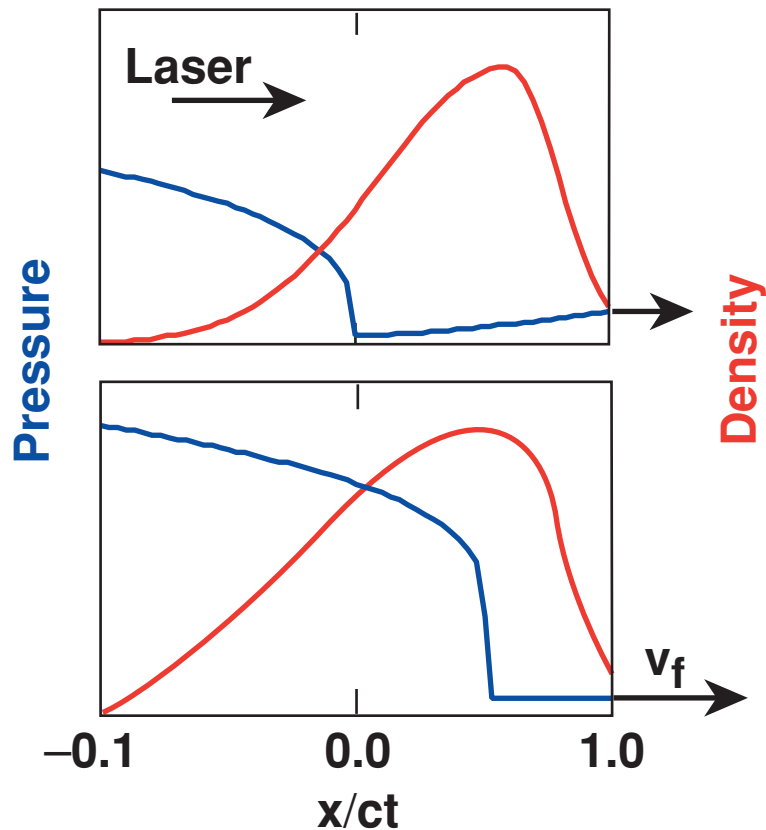
$\delta t$  varied between  
730 and 960 ps



$I_{\text{foot}}$  varied between  
1 and 6 TW



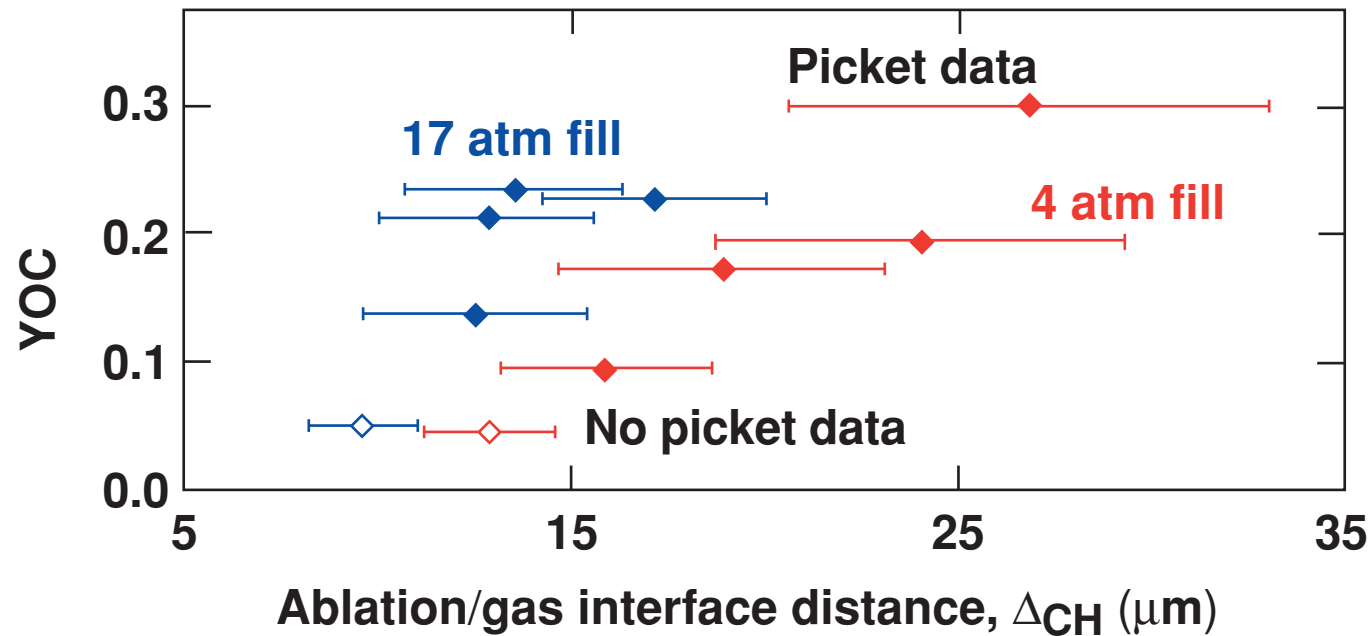
Picket timing relative to the drive pulse ( $\delta t$ ) changes the distance between the ablation and gas interfaces,  $\Delta_{CH}$



- Large  $\delta t$  – Decaying shock wave reaches rear of shell before compression wave
- Small  $\delta t$  – Compression wave catches decaying shock wave before rear of shell

- $v_f$  is larger when the compression wave overtakes the decaying shock wave in the shell.
- $\Delta_{CH}$  is larger and continues to grow.

# Experimental yield/1-D yield (YOC) is sensitive to the timing of the picket pulse relative to the drive pulse



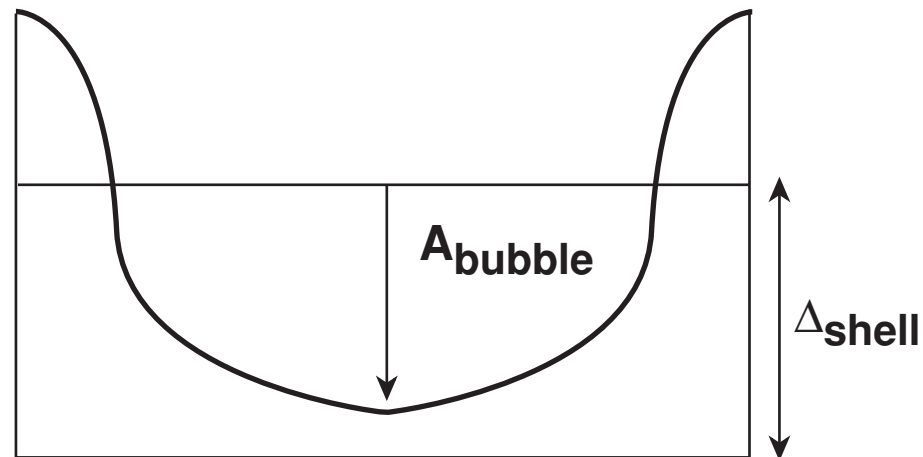
$$\Delta_{CH} \equiv \langle r_{\text{ablation}} - r_{\text{gas}} \rangle_t$$

- 4-atm-gas-filled targets travel farther during the deceleration phase.



# Both picket and non-picket pulse shapes were used to change the ablation-interface amplitude, $A_{\text{ablation}}$

- Separation of ablation and shell-gas interfaces =  $18 \pm 2 \mu\text{m}$

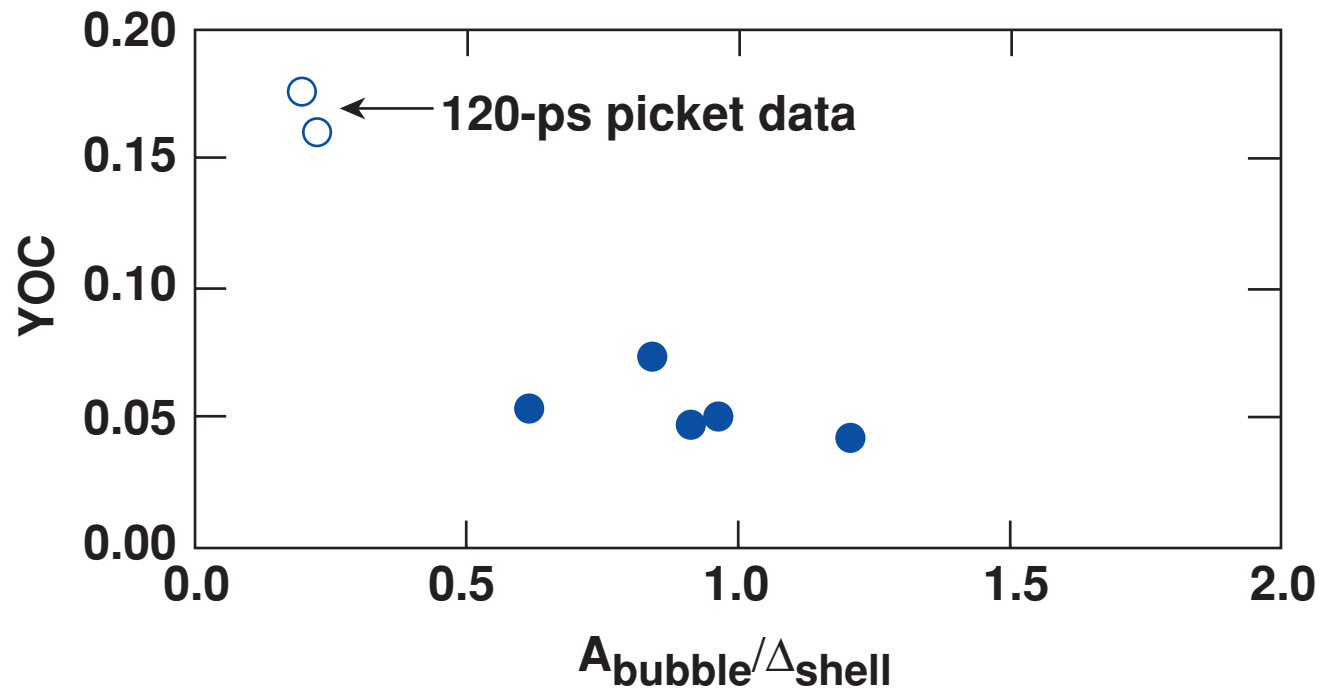


$$A_{\text{bubble}} = a_0 e^{\gamma t}$$

$$\gamma = 0.9 \sqrt{[kg/(1+kL)]} - 1.7 kV_a$$

# Acceleration-phase stability growth affects the ratio of the experimental yield to the 1-D simulation yield

- Separation of ablation and shell–gas interfaces,  $\Delta_{CH} = 18 \pm 2 \mu\text{m}$



- Bubble amplitude is calculated using postprocessor<sup>1</sup> to 1-D code *LILAC*.
- Calculation includes 1-Thz, 2-D SSD and interface roughness.

## **Shaped pulses have been used to control the seed amplitude of the deceleration-phase instability**

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