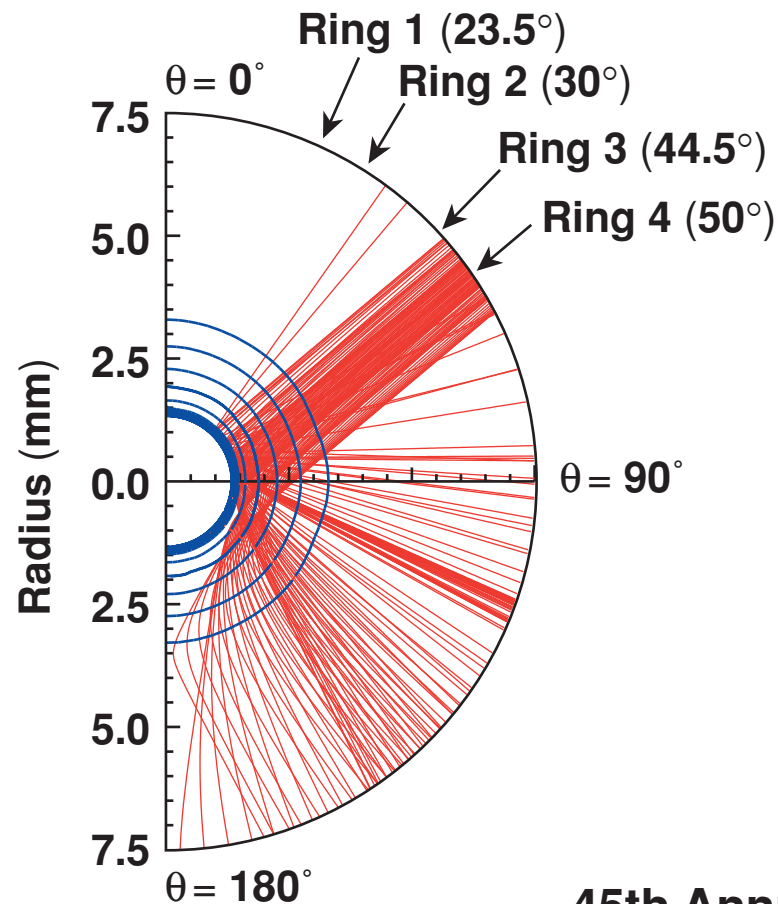


# Hydrodynamic Simulations of Polar Direct Drive on the NIF and LMJ Based on Three-Dimensional Ray Tracing



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## Summary

# Polar direct drive is a promising approach for studying ignition physics on both the NIF and the LMJ

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- 2-D implosions are driven by full 3-D ray tracing for all rings of beams.
- Elliptical phase plates are used for some beams.
- Implosion velocities at the end of the laser pulse are uniform to 3%–5% (rms).

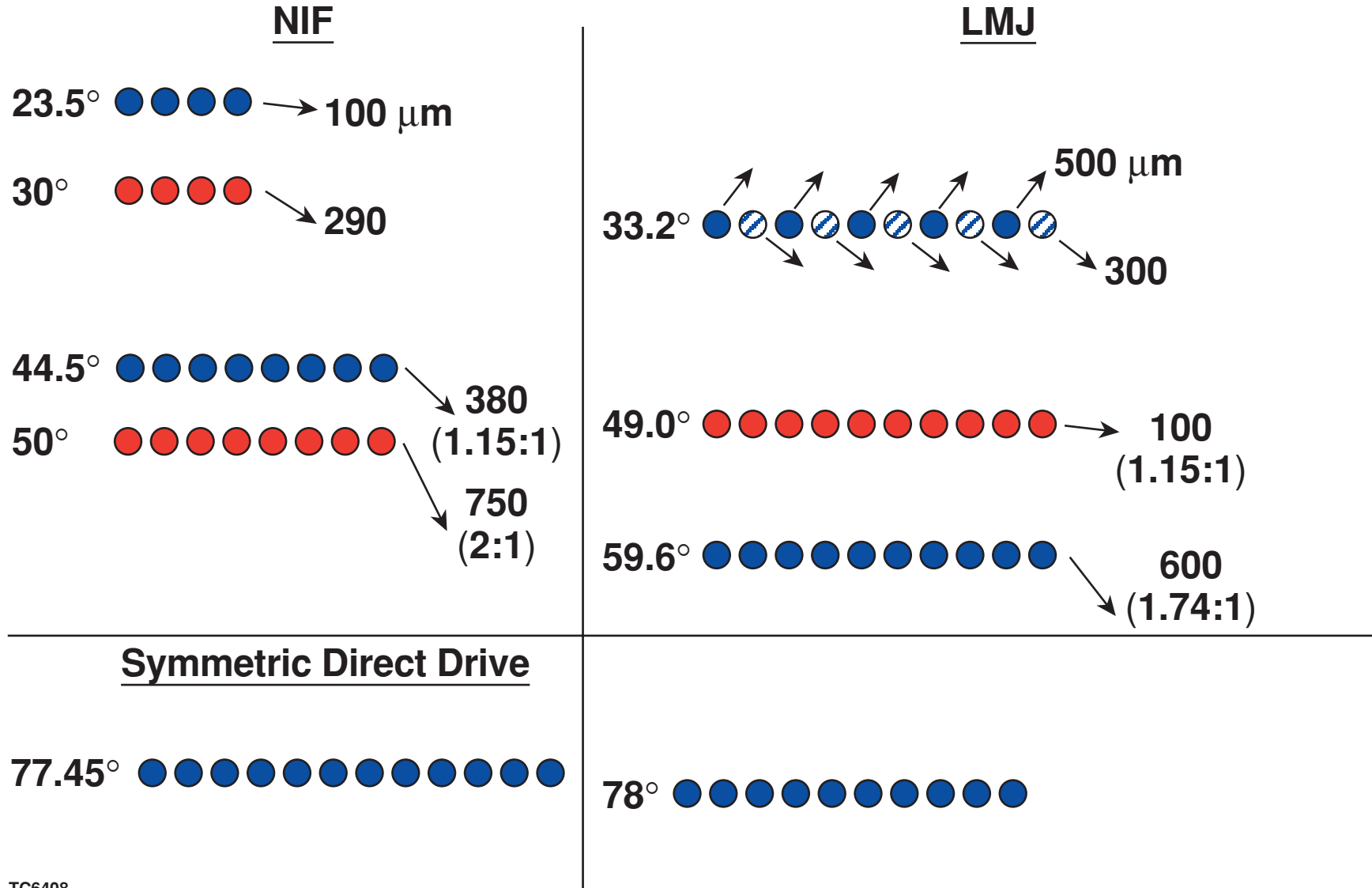
# Outline

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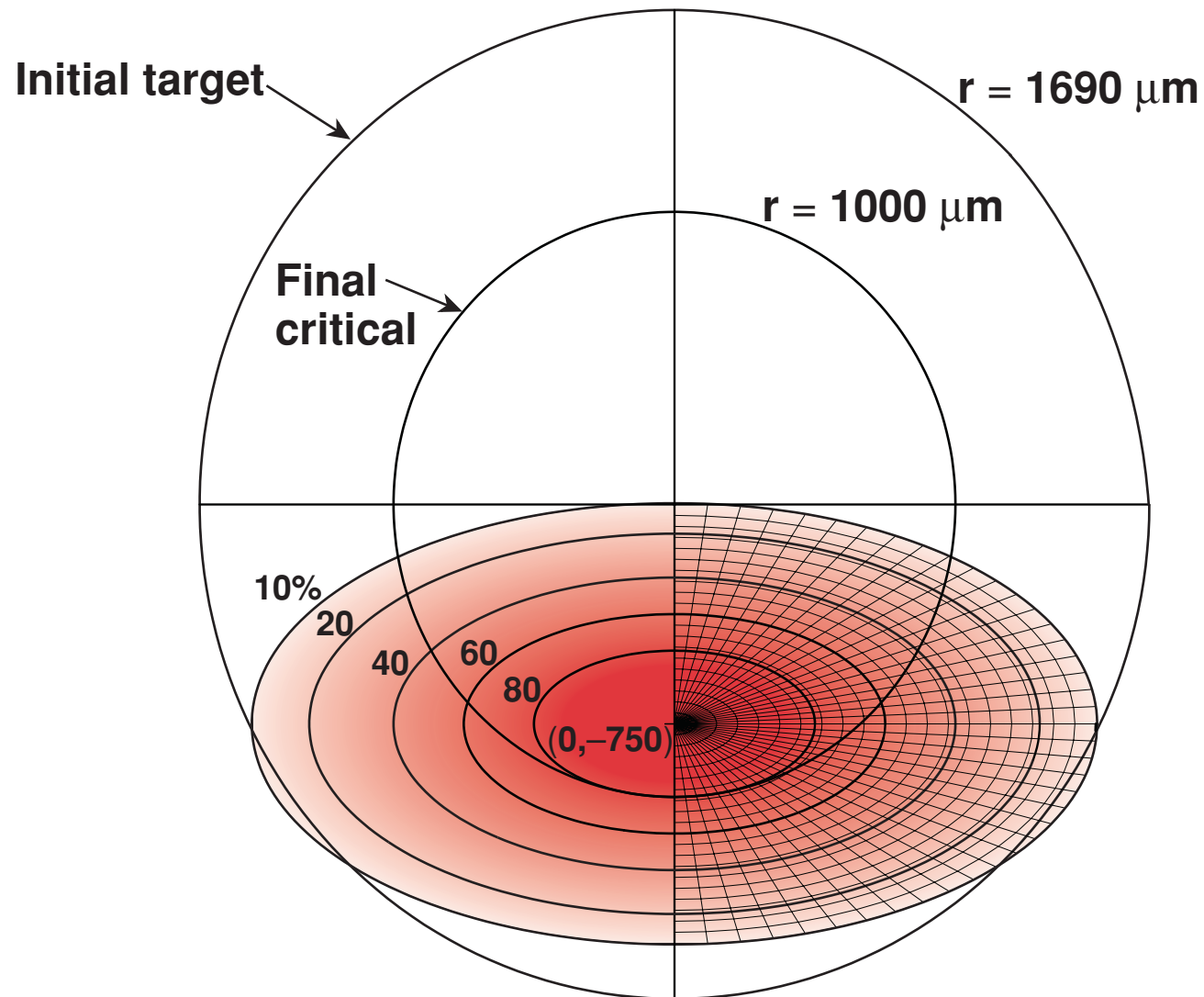


- **Irradiation/target designs for polar direct drive**
- **Comparison of “polar” and “symmetric” cases for both the NIF and the LMJ**
  - **t = 5.8 ns (just before shock breakout)**
  - **t = 9.0 ns (end of laser pulse)**

# The different NIF and LMJ configurations lead to different designs for polar direct drive



For the NIF, ring-4 beams are repointed 750  $\mu\text{m}$  and use 2:1 elliptical phase plates



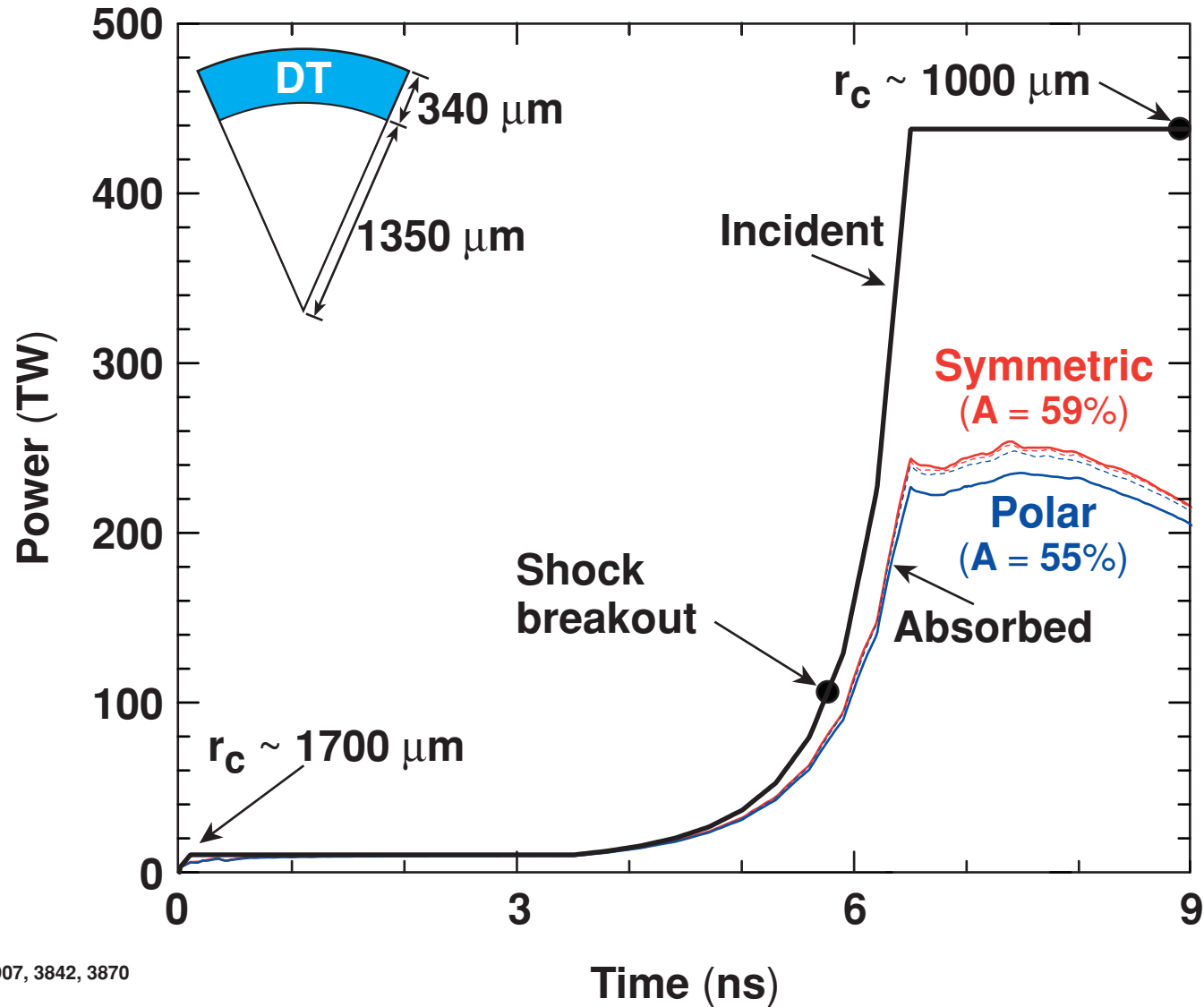
# A large parameter space is being explored

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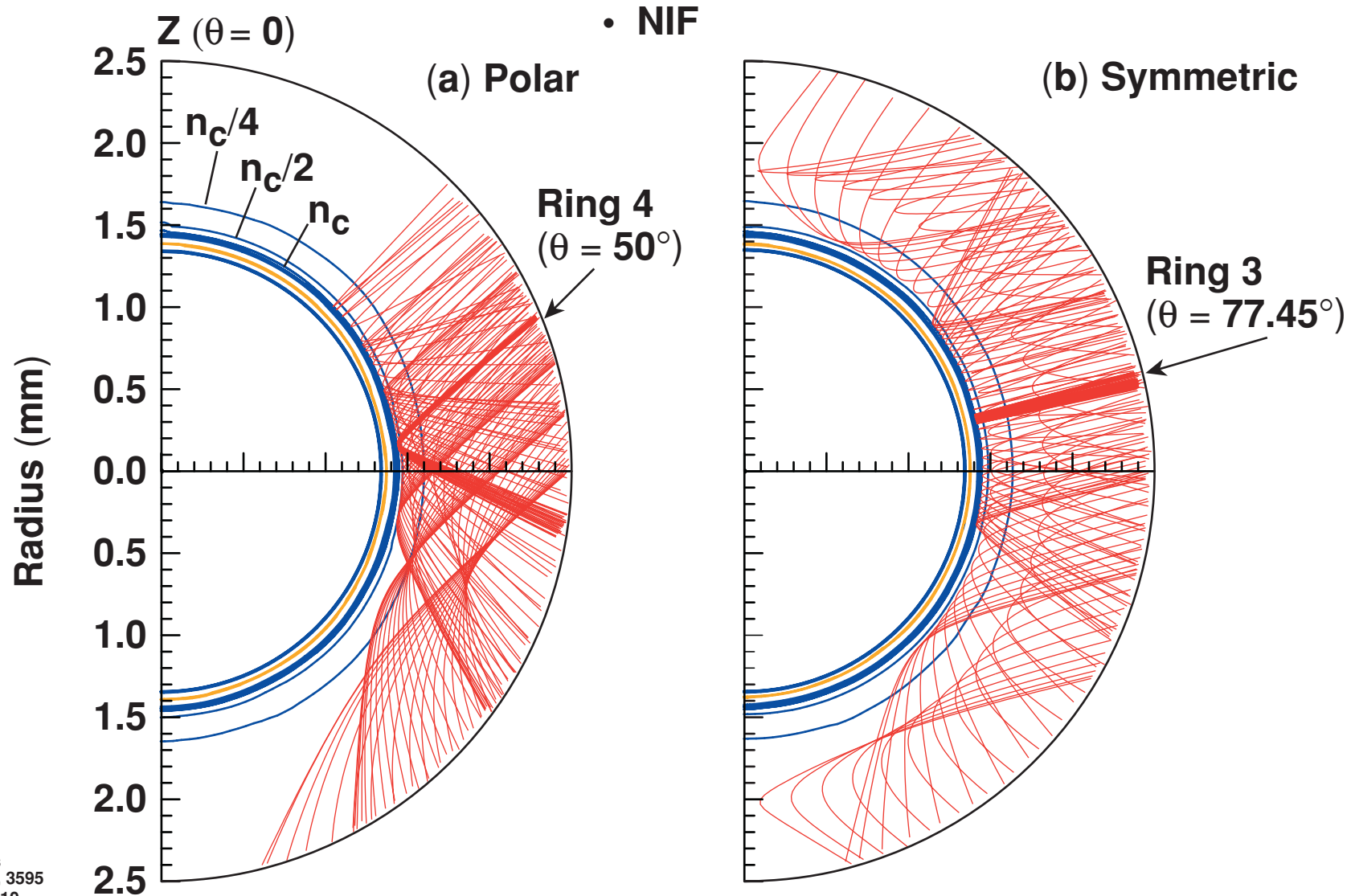
- These calculations have used
  - beam-pointing shifts
  - elliptical phase plates
  - varying spatial profiles\*
  - varying beam energies
- Future calculations will consider
  - varying temporal profiles
  - modified target designs
  - shimmed targets

$$* I(r) \propto \exp - (r/1200 \mu\text{m})^{2.5}$$

# The polar designs result in small absorption losses for both laser systems



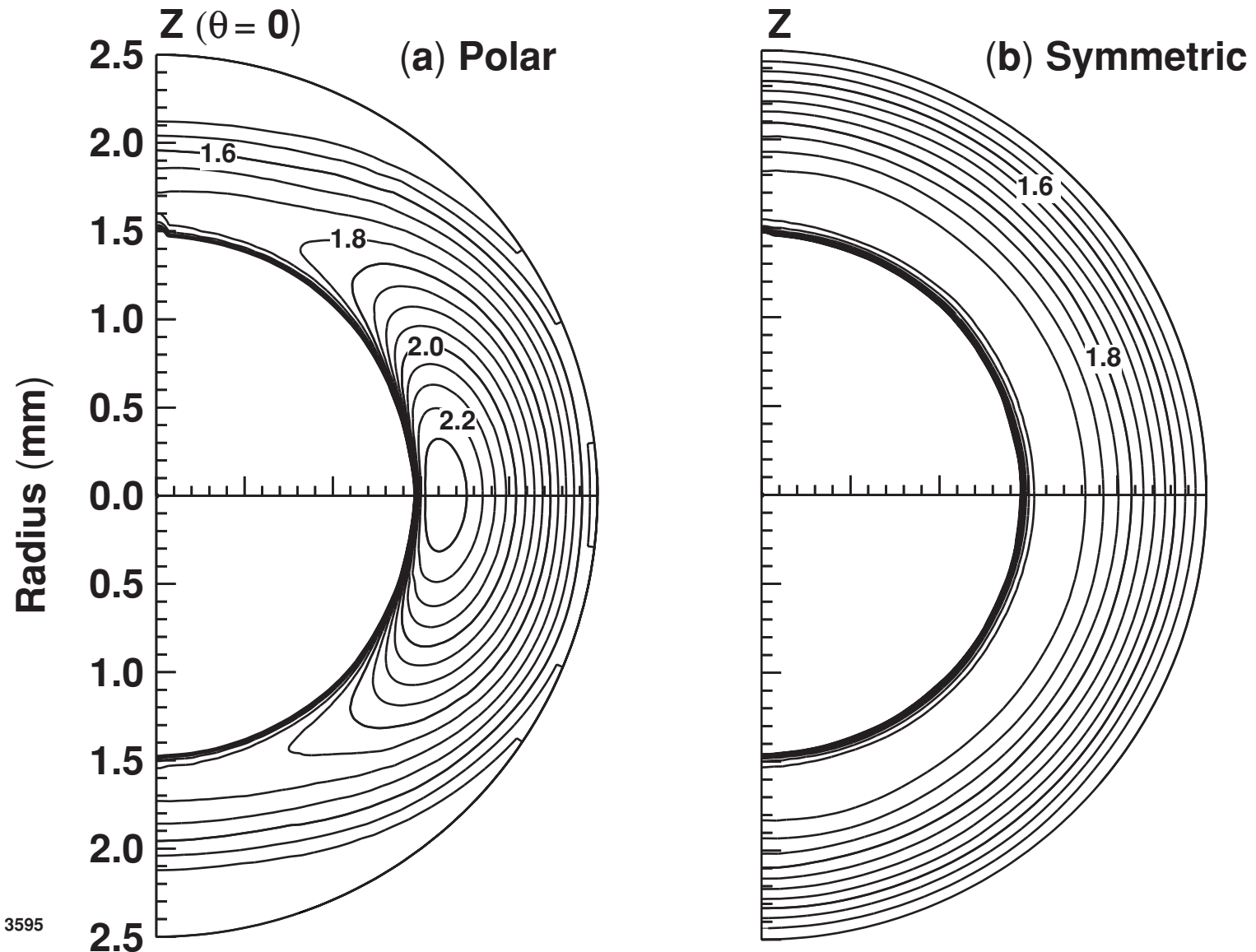
At 5.8 ns, a nearly spherical shock approaches the inner ice surface for both polar and symmetric drive





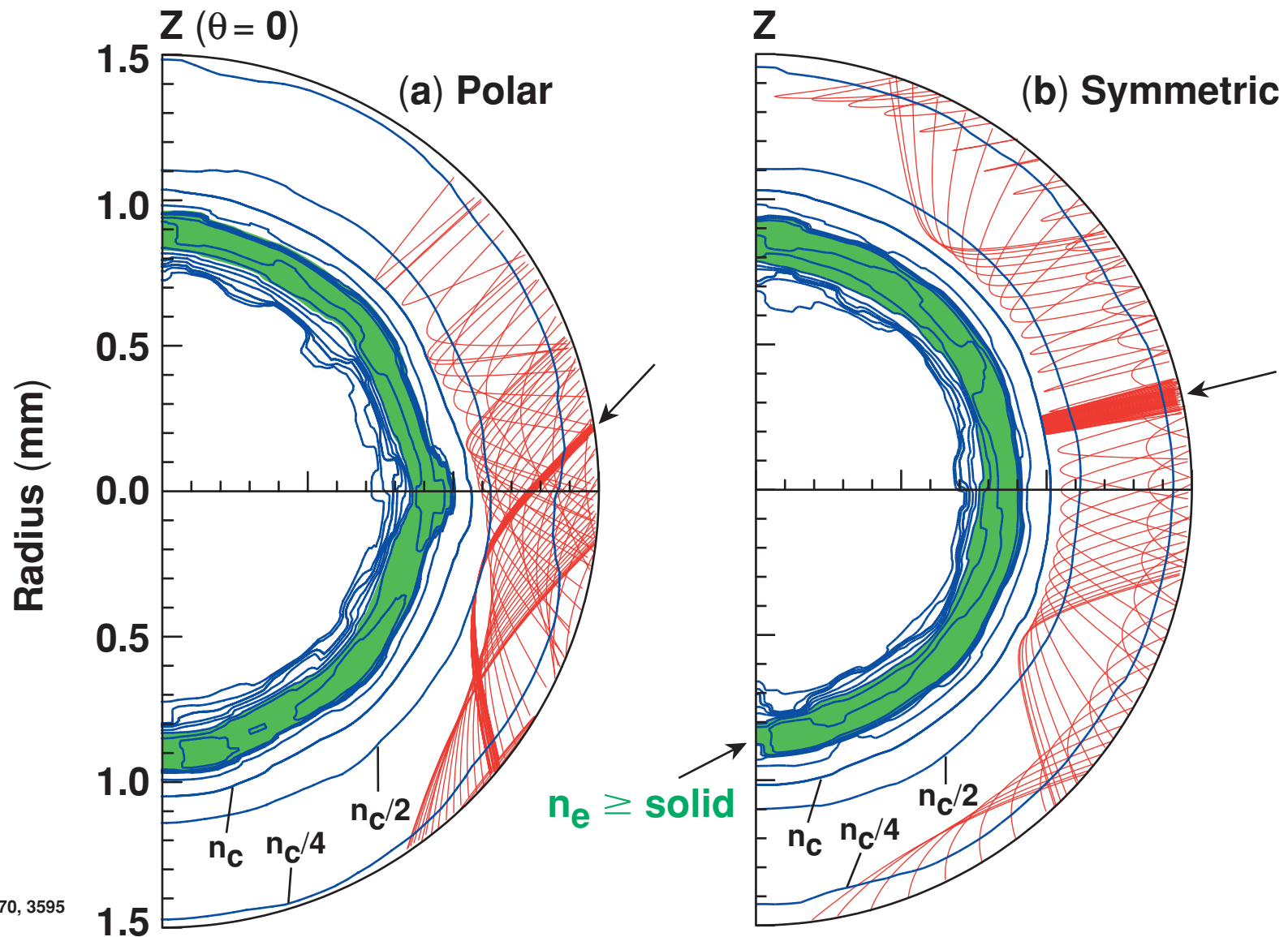
At 5.8 ns, the electron-temperature contours in the polar case show an  $\sim 10\%$  enhancement near the equator

• NIF

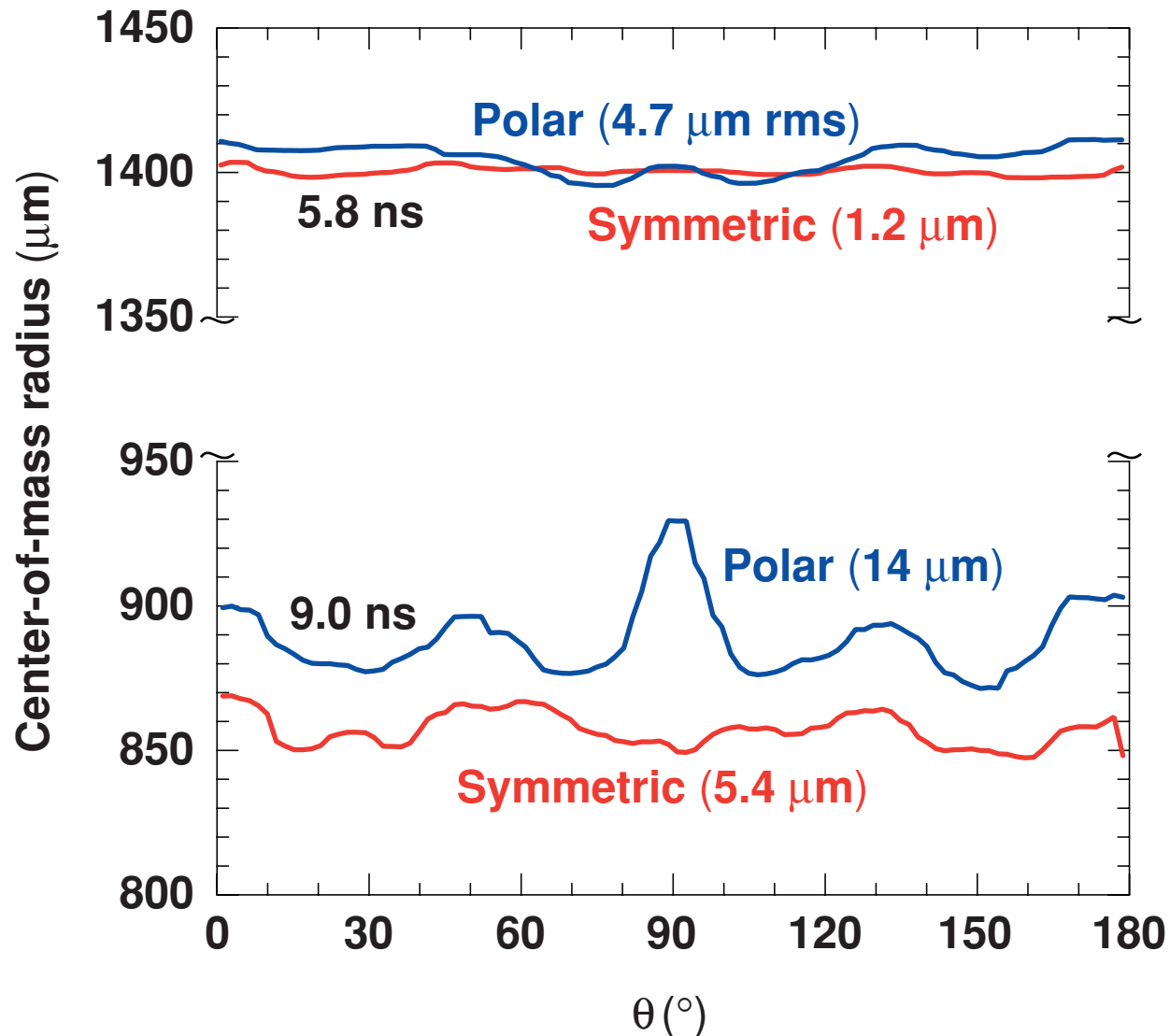


At the end of the laser pulse (9 ns), the polar case is almost as uniform as the symmetric case

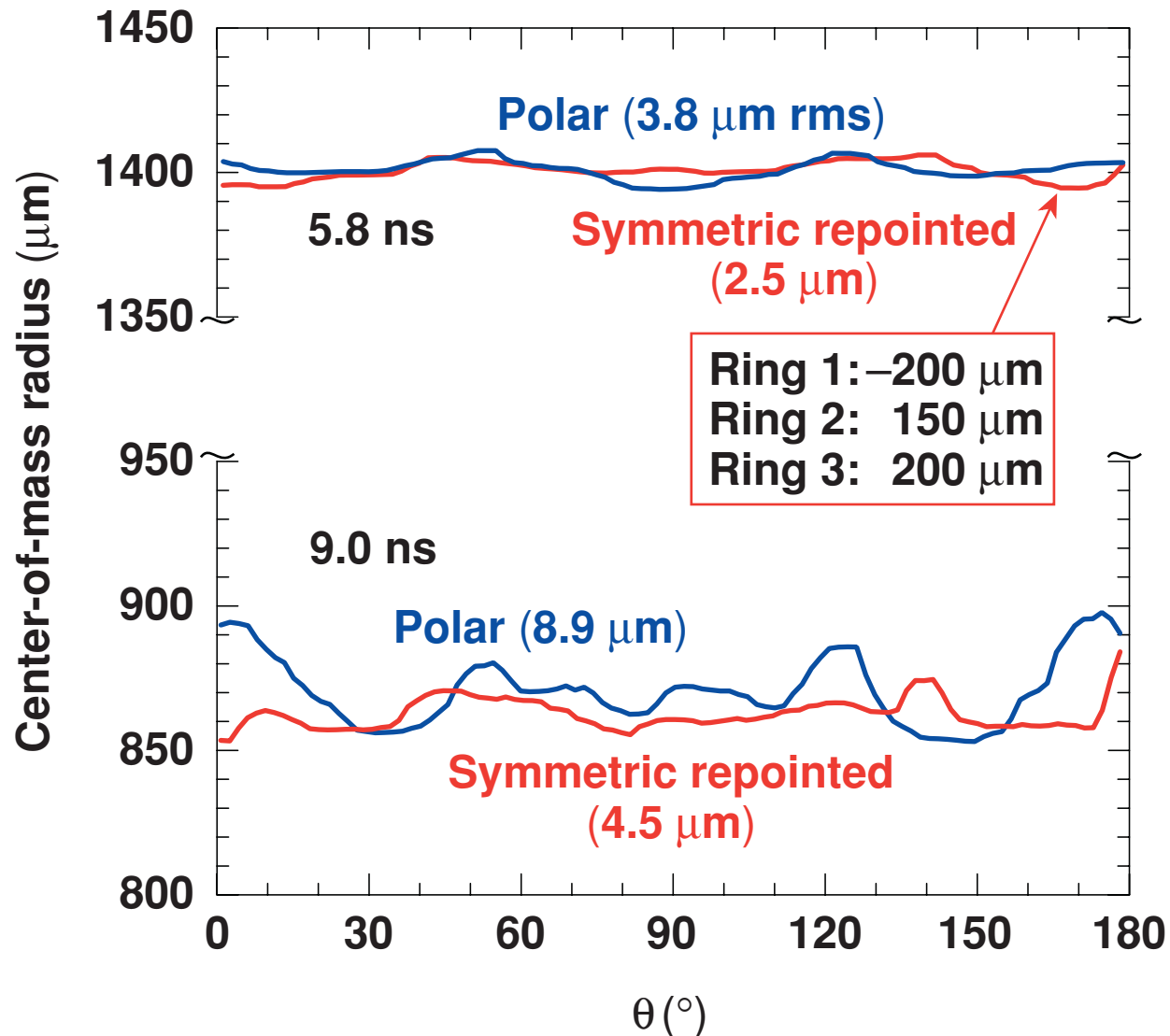
• NIF



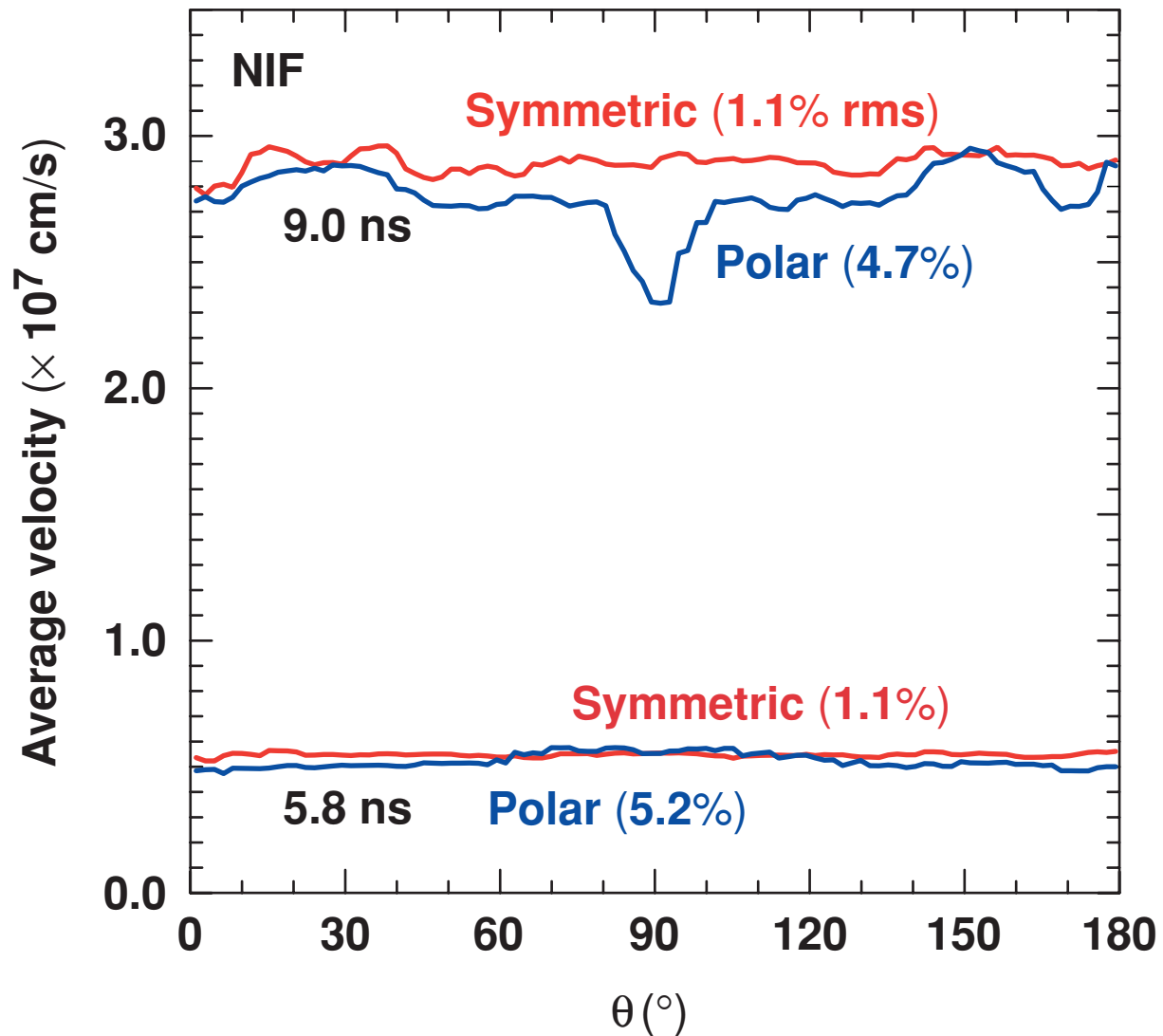
At 9 ns, the error in the center-of-mass radius of accelerated DT for the NIF polar design is greatest near the equator



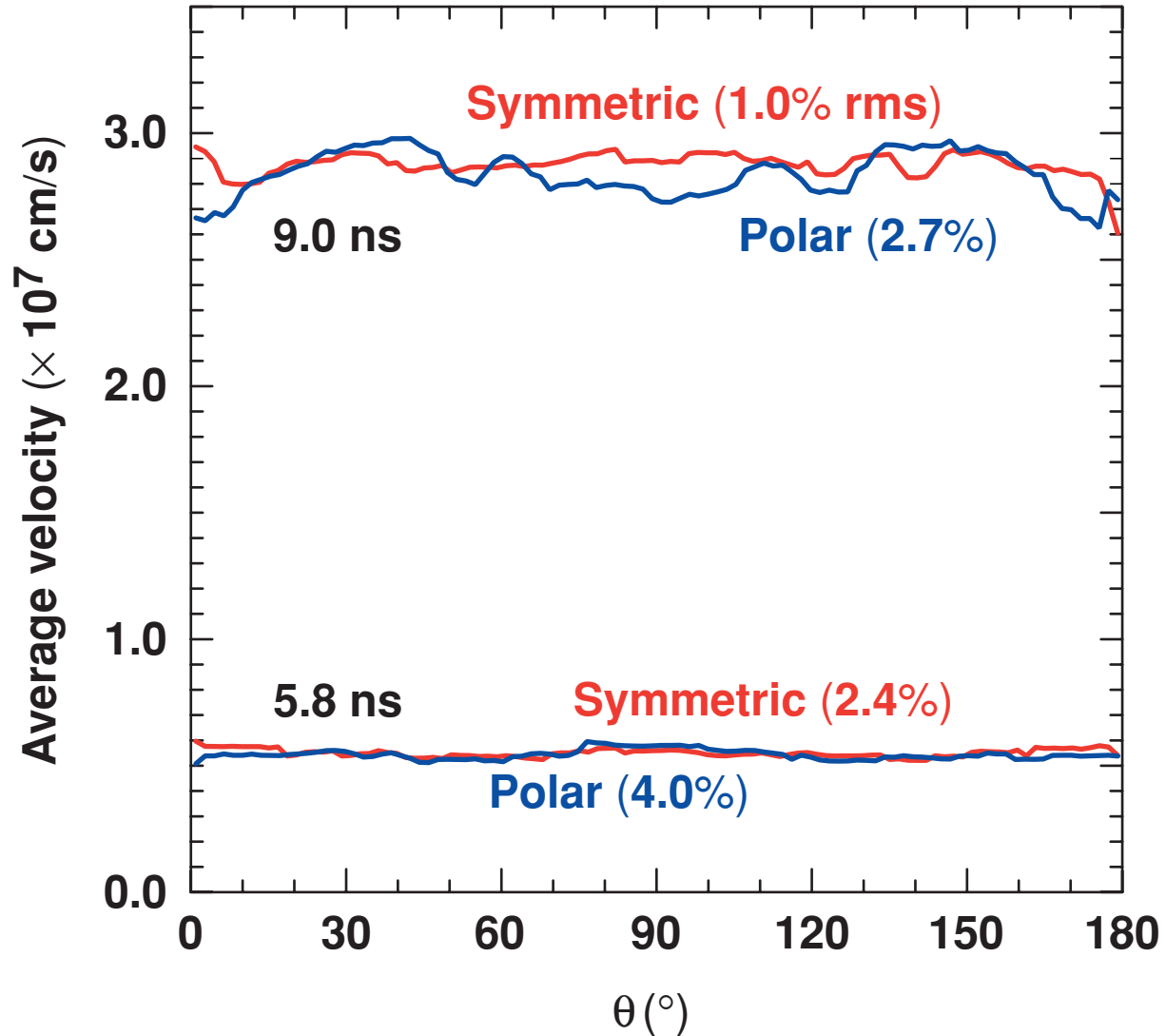
# At 9 ns, the error in the center-of-mass radius of accelerated DT for the LMJ polar design is greatest near the poles



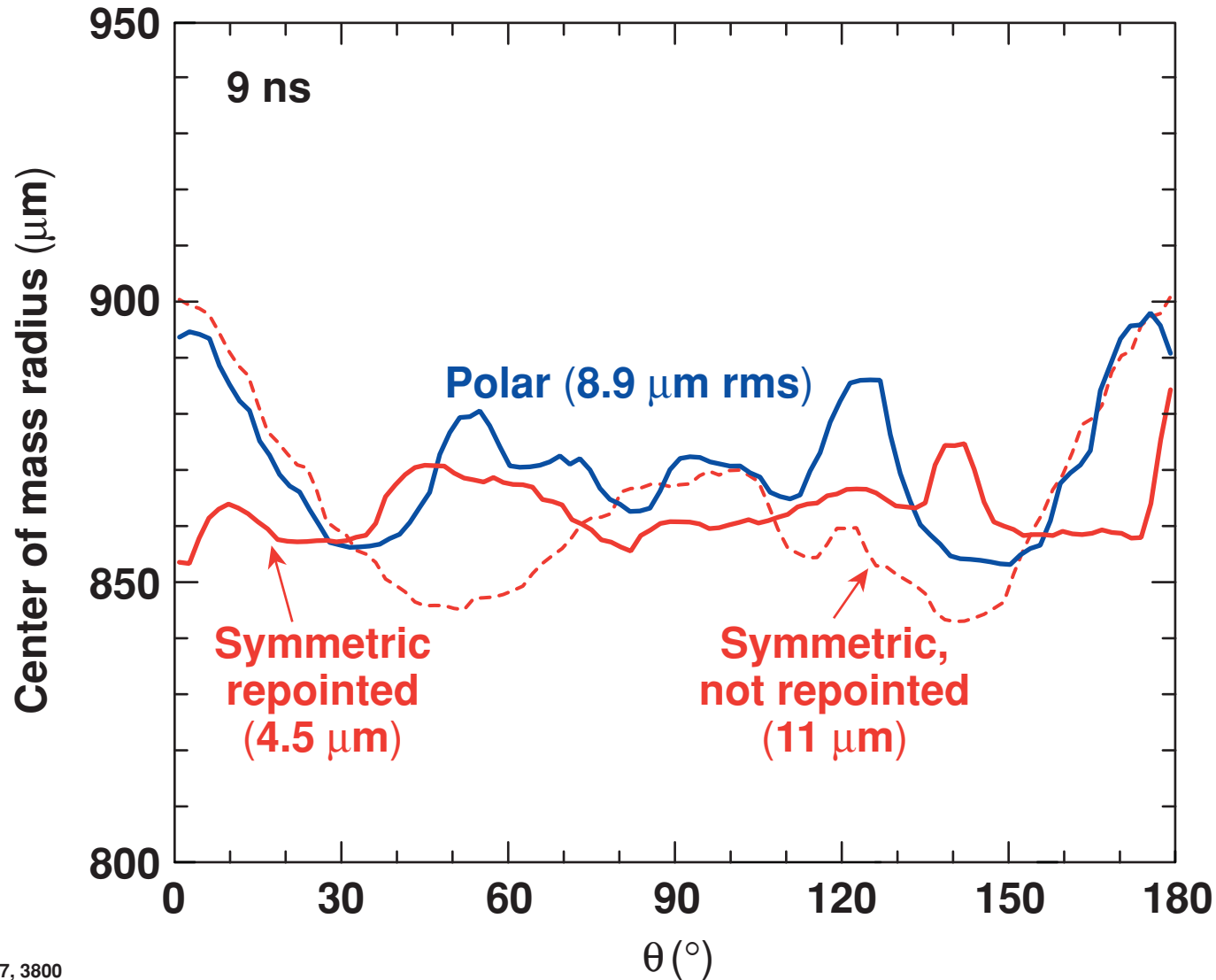
# At 9 ns, the average velocity of accelerated DT is low near the equator for the NIF polar design



# The problem at the equator is less for the LMJ



# For symmetric drive on the LMJ, better results are obtained with modest beam repointings



# Deviations in mean velocity are (not surprisingly) smaller for symmetric irradiation

- rms velocity variation at 9 ns

|                                    | <b>NIF</b>  | <b>LMJ</b>  |
|------------------------------------|-------------|-------------|
| <b>Polar</b>                       | <b>4.7%</b> | <b>2.7%</b> |
| <b>Symmetric (no repointing)</b>   | <b>1.1%</b> | <b>2.0%</b> |
| <b>Symmetric (with repointing)</b> | <b>—</b>    | <b>1.0%</b> |



## Summary/Conclusions

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- 2-D implosions are driven by full 3-D ray tracing for all rings of beams.
- Elliptical phase plates are used for some beams.
- Implosion velocities at the end of the laser pulse are uniform to 3%–5% (rms).

**The next step is to include modest pulse-shape variations.**