In-Situ Measurements of Direct-Drive **Illumination Uniformity on OMEGA**



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Image after correction for limb brightening



Experiments performed on the OMEGA Laser System have measured the 60-beam, direct-drive illumination uniformity

- The Legendre modes (ℓ < 30) UV illumination variations are inferred from images of x-ray emission from Au-coated spherical targets (at $I \approx 7 \times 10^{14}$, 100-ps pulses)
- Inference of illumination uniformity has been performed under best current conditions (clean debris shields, precision pointing, good beam balance)
- Beam-overlap illumination variation and stalk shadowing have both been observed with this method
- The $\sigma_{\rm rms}$ uniformity for standard-size targets (860- μ m diam) approaches 1% (with less than 1% in all low ℓ -modes above $\ell = 2$, individually and combined)





Collaborators

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The emission from spherical, Au-coated targets is corrected for limb brightening* to infer the local x-ray surface flux



E11296a



*F. J. Marshall *et al.*, Phys. Plasmas <u>11</u>, 251 (2004); R. A. Forties and F. J. Marshall, Rev. Sci. Instrum. <u>76</u>, 073505 (2005). CID: charge-injection device

When corrected for limb brightening, the x-ray images reveal peaks at the beam overlaps and low mode variation



for limb brightening

Limb-brightened image (uncorrected) Median filtered 60-μm region

E28007



TIM: ten-inch manipulator XRPHC: x-ray pinhole camera

The inferred UV illumination variation is determined from the x-ray emission variation using a power law







*F. J. Marshall et al., Phys. Plasmas 11, 251 (2004).

The depth of a stalk shadow is inferred from the assumed power law correspondence



This target stalk is in the same direction as current cryogenic targets.

E28009

Viewing camera image of target

Corrected images must be reprojected and combined to infer the illumination variation over the target surface

$$I_{\boldsymbol{x}}(\boldsymbol{\theta},\boldsymbol{\varphi}) = \frac{\sum f_{\boldsymbol{x}_{i}}(\boldsymbol{\theta},\boldsymbol{\varphi}) \boldsymbol{w}_{i}(\boldsymbol{\theta},\boldsymbol{\varphi})}{\sum \boldsymbol{w}_{i}(\boldsymbol{\theta},\boldsymbol{\varphi})}$$

where $I_x(\theta, \varphi)$ is the relative intensity at (θ, φ) , f_{x_i} is the contribution from the *i*th x-ray camera, and w_i is the weight

The cameras are cross-calibrated, the images reprojected and combined, after which the UV intensity variation is inferred using the power law correspondence

$$I_{\rm UV} \propto \left(I_{\rm X}
ight)^{(1/\gamma)}$$

The ten nearly identical CID-based XRPHC images (six TIM based, four fixed) are used to compute the full-sphere illumination uniformity.

Multiple XRPHC CID images of Au-coated targets are combined to determine the inferred UV illumination uniformity

E28011

TPS: Target Positioning System HED: high-energy diode

OMEGA direct-drive illumination uniformity inferred from x-ray images of Au-coated sphere emission approaches 1% rms

OMEGA shot 87286, uniformity target 858- μ m-diam, Au-coated sphere

Conditions: 60 UV beams, 100-ps pulse SG5 DPP's, 0.3-THz SSD, 3-color cycle 25 J/beam, 3.5% rms (beam-to-beam)

9 XRPHC-CID-image derived map

DPP: distributed phase plate SSD: smoothing by spectral dispersion p–v: peak-to-valley

The inferred low-mode OMEGA direct-drive illumination uniformity has no significant contributions above $\ell = 2$

E28089

Summary/Conclusions

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Isometric drawing of the interior of the OMEGA target chamber showing five fixed (yellow noses) and six TIM-based (blue noses) XRPHC's

E28090

Hammer–Aitoff projection of the OMEGA target chamber showing XRPHC locations: five fixed (yellow), 6 TIM-based (blue) XRPHC's

11 digitally recorded x-ray pinhole cameras record the target surface emission

